Taguchi optimization of machining parameters in drilling of AISI D2 steel using cryo-treated carbide drills

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Abstract. This study focused on using the Taguchi technique to optimize the process parameters in drilling of AISI D2 steel with carbide drills to minimize the surface roughness (Ra) and thrust forces (F_t). The drilling experiments were conducted on a CNC vertical machining centre according to the L18 experimental design. Uncoated drills were classified into three groups: untreated (U), cryo-treated (CT) and cryo-treated and tempered (CTT). The experimental results showed that the CTT drills exhibited the best performance in terms of Ra and F_t due to the improved wear resistance of carbide drills after the cryogenic treatment and tempering. As a result of analysis of variance (ANOVA), it was found that the most influential parameter on both Ra and F_t was the feed rate, with percentage contributions of 66.97% and 80.07%, respectively. The results showed that the Taguchi technique is a powerful method to optimize the process parameters in drilling of tool steel.

Keywords. Taguchi method; cryo-treatment; thrust force; surface roughness.

1. Introduction and literature review

Cryogenic treatment is a cooling process that is applied to metallic materials at cryogenic temperatures (e.g., -196°C) to obtain superior properties [1]. In recent decades, there has been increased interest in the application of cryogenic treatments to different materials. It has been reported that cryogenic treatment forms fine carbides and homogeneously distributes the carbide particles. Hence, the hardness and wear resistance of the treated tool material improve. In addition, lower cutting forces and surface roughness can be obtained because the micro-structure improves after the cryogenic treatment [2]. Bal [3] investigated the effects of cryogenic treatment (at -190°C for 24 h) on the cutting performance of uncoated tungsten carbide inserts in turning. The experimental results showed that the cryogenic treatment increased the fracture toughness and decreased the amount of flank wear and the measured cutting forces. Thakur *et al* [4] reported that controlled cryogenic treatment improved the wear resistance because of the physical changes, i.e., the densification of the cobalt metal binder that firmly holds the carbide particles. Reddy *et al* [5] evaluated the machinability of the C45 steel workpiece in terms of the flank wear of the cutting tool inserts, the main cutting force and the surface finish of the

machined workpieces. The coated tungsten carbide inserts were subjected to deep cryogenic treatment (-176°C). The turning test results showed that the treated carbide tools had less flank wear, lower cutting forces and lower surface roughness than untreated ones. Yong [6] declared that the cryogenic treatment significantly improved the micro-structure of tungsten carbide by increasing the size and quantity of the β -phase, whereas the η -phase and γ -phase exhibited corresponding decreases. Dogra *et al* [7] claimed that the thermal conductivity of cemented tungsten carbide increased after the cryogenic treatment. Therefore, a longer tool life was obtained for carbide inserts because of the lower cutting temperature during the finish hard turning. Because the micro-structure of the tungsten carbide tools improved, their wear resistance increased. Many studies in the literature reported that cryogenic treatment led to homogeneous micro-structure, better wear resistance [8–10], better fracture toughness, longer tool life, lower cutting forces and lower surface roughness [11–17].

The Taguchi design is an efficient and effective experimental method in which a response variable can be optimized with various control factors and noise factors, using fewer resources than those of a factorial design [18, 19]. Currently, the Taguchi technique is increasingly used because it significantly reduces the required number of experimental studies. Asiltürk and Akkuş [20] used the Taguchi technique to minimize the surface roughness of

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hardened AISI 4140 steel after turning experiments with coated carbide cutting tools.

The results of the study showed that the feed rate affected the surface roughness the most. The authors claimed that the developed model could effectively determine the optimum cutting parameters to minimize surface roughness. Göloğlu and Sakarya [21] aimed to investigate the optimum cutting characteristics of a DIN 1.2738 mold steel using high-speed steel end mills and to identify the effects of the cutter path strategy in pocket milling. The results showed that the most influential parameters are the feed rate for one direction and spiral cutter path strategies and the depth of cut for the back-and-forth cutter path strategy. Vijian and Arunachalam [22] analysed the influence of the process parameters on the surface roughness in the squeeze casting process of LM6 aluminum alloy using the Taguchi method. The results indicated that the squeeze pressure and the die preheating temperature could significantly improve the surface finish of the squeeze-cast components. Tsao and Hocheng applied the Taguchi method to the process parameters (feed rate, spindle speed and drill diameter) to predict the thrust force and surface roughness of a candlestick drill in drilling composite materials. The authors found that the feed rate and drill diameter were the most significant factors that affected the thrust force, whereas the feed rate and the spindle speed affected the surface roughness [23].

The objective of this study was to use the Taguchi technique to optimize the process parameters that affect R_a and F_f in drilling AISI D2 cold-work tool steel with cryogenically treated cemented carbide drills. In addition, this study focuses on the effects of cryogenic treatment, which is a drilling parameter, on R_a and F_f .

2. Experimental methods

In the drilling experiments, AISI D2 cold-work tool-steel blocks with dimensions of $100 \times 170 \times 12 \text{ mm}^3$ were used as the workpiece material. Drilling experiments were performed on a Johnford CNC vertical machining centre with a power of 10 kW and a maximum spindle speed of 8000 rev/min under dry conditions. The experimental set-up is shown in figure 1.

Uncoated cemented carbide drills with diameter of 5 mm, which were produced by Guhring Company, were used as the cutting tools. Based on the results of preliminary experiments and review of the Guhring Catalogue, three cutting speeds (50, 55 and 60 m/min), two feed rates (0.063 and 0.08 mm/rev) and a single depth of cut (7 mm) were selected as the cutting parameters. The cutting forces were measured using a Kistler dynamometer, which was fixed on the table of the CNC machine tool. Measurements of surface roughness (R_a), which was the most important component of the cutting forces in the drilling process,

Figure 1. Experimental set-up.

Table 1. Drill properties.

Drill type	Helix drill
Standard	DIN 6539
Drill material	WC
Diameter	5 mm
Tip angle	135°
Helix angle	35°
Helix length	26 mm
Drill length	62 mm

were considered in this study [15, 16]. To obtain the optimal thrust forces, three holes were drilled for the same combination of cutting parameters, and the mean value of the measured thrust forces was accepted as the F_f value. The surface roughness was measured using a Mitutoyo Surftest SJ-301 surface roughness tester. The tool-steel blocks were sliced along the centres of the holes using a wire EDM machine to reach their sidewalls, and R_a was measured from those sides. To obtain accurate R_a values, the R_a measurements were repeated three times and along 5 mm in length on different surface regions of the hole wall, and the mean value of these measurements was selected as the R_a value. The uncoated tools were subjected to deep cryogenic treatment at -196°C for 24 h and tempering at 200°C for 2 h to observe their effects on the surface roughness, thrust forces and wear resistance. Carbide drills (table 1) were used in the experiments.

Cryogenic process has been applied to drills. Thus, three types of the drills were used in the experiments: untreated (U), cryo-treated (CT) and cryo-treated and tempered (CTT). The drills were gradually cooled to cryogenic temperatures and gradually heated to room temperature to avoid thermal cracks caused by sudden changes in temperature [24, 25]. To determine the correlation among F_f , R_a and the wear and to observe the contribution of the cryogenic treatment and

Table 2. Process parameters and levels.

Symbol	Parameter	Levels		
		1	2	3
A	f	0.063	0.08	–
B	V	50	55	60
C	Ct	U (untreated)	CT (cryogenic)	CTT (cryo-tempering)

tempering to the wear resistance, a number of wear experiments were performed at a cutting speed of 65 m/min and a feed rate of 0.08 mm/rev. In the wear experiments 330, 400 and 500 holes were drilled in the cold-work tool-steel plates using different carbide tools, and SEM images were taken to specify the wear types that formed on the drill tip. By performing micro-hardness measurements at four different points on the tool surface, the mean value of four measurements was determined as the micro-hardness value. The micro-hardness measurements were conducted under a load of 200 g that was applied for 10 s.

3. Experimental design and optimization

3.1 Taguchi experimental design approach

Optimization of the process parameters is the key step in the Taguchi method to achieve high quality without increasing the cost. Basically, the classical process parameter design is complex and difficult to use [26]. The Taguchi method experiment design incorporates orthogonal arrays, which were developed by Taguchi to successfully design and conduct fractional factorial experiments that can collect all statistically significant data with the minimum possible number of repetitions [27]. The Taguchi method has several types of quality characteristics, such as “nominal is best”, “smaller is better” and “larger is better”. The minimum value is taken for the best surface roughness (Ra) and thrust forces (Ff). Hence, in this study, “smaller is better” was selected as a performance characteristic to calculate the S/N ratio because the minimal surface roughness and minimal thrust force were optimal for better product quality, longer component and tool lives and minimal costs. Therefore, based on the Taguchi method, the S/N ratio calculation was decided as “smaller is better” as given in the following equations [28]:

$$\text{Smaller is better } S/N = -10 \log \left(\frac{1}{n} \sum_{i=1}^n y_i^2 \right). \quad (1)$$

3.2 Control factors and orthogonal array

In the Taguchi method, orthogonal arrays can provide an effective experimental performance with a minimum

Table 3. The orthogonal array L_{18} ($3 \times 3 \times 2$).

Trial no.	A	B	C
1	1	1	1
2	1	1	2
3	1	1	3
4	1	2	1
5	1	2	2
6	1	2	3
7	1	3	1
8	1	3	2
9	1	3	3
10	2	1	1
11	2	1	2
12	2	1	3
13	2	2	1
14	2	2	2
15	2	2	3
16	2	3	1
17	2	3	2
18	2	3	3

number of experimental trials [29]. Therefore, the selection of a suitable orthogonal array for the cutting parameters is fundamental in the Taguchi method. In this paper, L_{18} ($3 \times 3 \times 2$), which is the most suitable orthogonal array, was selected to determine the optimal drilling parameters and analyse their effects on the surface roughness and the thrust force. The cutting tools (Ct), the cutting speed (V) and the feed rate (f) were selected as the control factors that affect the surface roughness and the thrust force, and their levels were selected as shown in table 2. The cutting parameters used for the selected orthogonal array and their 18 combinations were constructed as shown in table 3.

4. Experimental results and discussion

4.1 Signal-to-noise (S/N) ratio

The Taguchi method uses S/N ratios to measure variations in the experimental design [29]. In the study, the performance characteristic “smaller is better” was selected to calculate the S/N ratios because the lowest values of surface roughness and thrust force are optimal for product quality, tool life and power consumption. The calculated S/N ratios for the surface

Table 4. *S/N* ratios for surface roughness and thrust force.

Trial no.	Cutting parameter level			Measured surface roughness Ra (μm)	<i>S/N</i> ($n_i = 1-18$) dB	Measured thrust force Ff (N)	<i>S/N</i> ($n_i = 1-18$) dB
	A Feed rate (<i>f</i>)	B Cutting speed (<i>V</i>)	C Cutting tool (Ct)				
1	0.063	50	U	2.20	−6.85	771	−57.74
2	0.063	50	CT	2.01	−6.06	750	−57.50
3	0.063	50	CTT	1.91	−5.62	741	−57.40
4	0.063	55	U	1.95	−5.80	755	−57.56
5	0.063	55	CT	1.92	−5.67	748	−57.48
6	0.063	55	CTT	1.82	−5.20	736	−57.34
7	0.063	60	U	1.80	−5.11	747	−57.47
8	0.063	60	CT	1.74	−4.81	740	−57.38
9	0.063	60	CTT	1.65	−4.35	730	−57.27
10	0.08	50	U	2.65	−8.46	900	−59.08
11	0.08	50	CT	2.43	−7.71	882	−58.91
12	0.08	50	CTT	2.38	−7.53	842	−58.51
13	0.08	55	U	2.6	−7.82	875	−58.84
14	0.08	55	CT	2.25	−7.04	860	−58.69
15	0.08	55	CTT	2.20	−6.85	796	−58.02
16	0.08	60	U	2.31	−7.27	850	−58.59
17	0.08	60	CT	2.20	−6.85	840	−58.49
18	0.08	60	CTT	2.10	−6.44	793	−57.99

Table 5. Response table of *S/N* ratios and mean values.

Control factors	Thrust force (Ff)				Surface roughness (Ra)			
	Level 1	Level 2	Level 3	Delta	Level 1	Level 2	Level 3	Delta
<i>S/N</i> ratios								
A	−57.6	−58.57	–	1.11	−5.496	−7.332	–	1.835
B	−58.19	−57.99	−57.86	0.33	−7.040	−6.396	−5.805	1.235
C	−58.21	−58.07	−57.75	0.46	−6.885	−6.358	−5.999	0.886
Means								
A	746.4	848.7	–	102.2	1.889	2.331	–	0.442
B	814.3	795.0	783.3	31.0	2.263	2.100	1.967	0.297
C	816.3	803.3	773.0	43.3	2.228	2.092	2.010	0.218

roughness and thrust force are shown in table 4. In the experimental trials, the mean surface roughness was 2.11 μm , and the mean *S/N* ratio for this surface roughness value was −6.41 dB. The mean thrust force and its mean *S/N* ratio were 797.56 N and −58.01 dB, respectively.

The influences of each control factor (A, B and C) on the surface roughness and thrust force were analysed using a signal-to-noise ratio response table. The *S/N* ratio response tables for Ra and Ff are shown in table 5. They show the *S/N* ratio at each control factor level and how it changes when the settings of each control factor change from one level to another.

The optimal levels were found by evaluating different levels that were obtained from all combinations of control factors, which were constructed in the orthogonal array. The determined levels of the control factors for the surface roughness

and the thrust force are shown in table 5. The effects of the control factors and their levels on the surface roughness and the thrust force are illustrated in figures 2 and 3.

4.2 ANOVA

The ANOVA values of the experimental results for the surface roughness and the thrust force are shown in table 6. As shown in table 6, the percentage contributions of factors A, B and C to the surface roughness were 66.97%, 20.17% and 11.11%, respectively. The percentage contributions of factors A, B and C to the thrust force were 80.07%, 5.01% and 10.1%, respectively. These results show that factor A, the feed rate, was the most influential factor on both the surface roughness and thrust force.

Figure 2. Effects of the control factors on the thrust force.

Figure 3. Effects of the control factors on the surface roughness.

Table 6. ANOVA results for the surface roughness and thrust force.

Variance source	Sum of squares (SS)	Degree of freedom (df)	Mean square (MS)	F ratio	P	Contribution (%)
Thrust force (Ff)						
A	47,022	1	47,022	199.48	0.000	80.07
B	2942	2	1471	6.24	0.014	5.01
C	5934	2	2967	12.59	0.001	10.1
Error <i>e</i>	2829	12	236	–	–	4.82
Total	58,726	17	–	–	–	100
Surface roughness (Ra)						
A	0.880	1	0.880	462.94	0.000	66.97
B	0.265	2	0.132	69.69	0.000	20.17
C	0.146	2	0.073	38.41	0.000	11.11
Error <i>e</i>	0.023	12	0.002	–	–	1.75
Total	1.314	17	–	–	–	100

Table 7. Formula of confidence interval definitions [28].

No.	Symbol	Description	Value
1	$F_{\alpha;1;fe}$	F ratio at 95% (in F table)	18.51
2	α	Significance level	0.5
3	f_e	Degrees of freedom of error	2
4	V_e	Error variance	2
5	r	Number of replications for confirmation experiment	3
6	n_{eff}	Effective number of replications	3,856
7	N	Total number of experiments	27
8	T_{dof}	Total main factor degrees of freedom	6

4.3 Confirmation experiments

In the Taguchi technique, the reliability of the optimization is experimentally confirmed after the optimal results and their control factors and levels are determined. The optimal surface roughness (Ra_p) and optimal thrust force (Ff_p), which were predicted by the optimization process, were calculated by considering factors A_1 , B_3 and C_3 .

Confidence interval (CI) for surface roughness was calculated [28] using Eq. (2). Estimated values must be in the CI.

$$CI = \sqrt{F_{\alpha;1;fe} \cdot x V_e x \left(\frac{1}{n_{eff}} + \frac{1}{r} \right)} \quad (2)$$

where formula symbols and value for CI are shown in table 7.

The values of A_1 , B_3 and C_3 , which are the means of the experimental trials at their optimal levels, are 746.4, 783.3 and 773.0 N, respectively. Considering the optimum levels of factors A_1 , B_3 and C_3 , the optimal thrust force was 707.6 N. The mean values of factors A_1 , B_3 and C_3 at their optimal levels are 1.889, 1.967 and 2.010 μm , respectively. Considering the optimum levels of these factors, the optimal surface roughness is 1.650 μm . The results are analysed at a confidence level of 95%.

The CIs for the thrust force and surface roughness were calculated as 24.3 N and 0.07 μm , respectively. With a 95%

confidence level, the results of the confirmation tests that were conducted for the thrust force should be in the (CI) of (707.6 $\pm$ 24.3) or (683.3 – 731.9) N. The mean of the measurements in three confirmation tests, which were conducted for the optimal levels (A_1 , B_3 , C_3), was 730.944 N. The surface roughness was similarly calculated and should be in the (CI) of (1.65 $\pm$ 0.07) or (1.58 – 1.72) μm . The surface roughness and thrust force were systemically optimized using the Taguchi method at a significance level of 5%.

The surface roughness and thrust force values were compared according to the optimal test and the predicted combination, and the combination of (A_2 , B_3 , C_1) was selected randomly from 18 initial trials, as shown in table 8. According to these comparisons, the surface roughness and thrust force were reduced from 2.31 to 1.65 μm and from 850 to 707.6 N, respectively. The accuracy was improved by 29% and 17% for the surface roughness and the thrust force, respectively, because of the optimal combination.

5. Experimental evaluations

The hardness values of the untreated and treated drills are shown in figure 4. The hardness value of the CT drill increased by approximately 5% (from 1166 to 1232 Hv_{0.2})

Table 8. Comparison of the surface roughness and the thrust force.

	Level	Surface roughness		Thrust force	
		Ra (μm)	S/N (dB)	Ff (N)	S/N (dB)
Initial combination	A ₂ B ₃ C ₁	2.31	−7.27	850	−58.59
Optimal combination (experiment)	A ₁ B ₃ C ₃	1.65	−4.35	730	−57.27
Optimal combination (prediction)	A ₁ B ₃ C ₃	1.64	−4.33	730.94	−57.27

Figure 4. Micro-hardness values of U, CT and CTT drills.

with respect to the U drill after the deep cryogenic treatment at -196°C for 24 h. After the tempering process at 200°C for 2 h, the hardness decreased by 2% because of the effects of the high temperature.

The surface roughness varied depending on the cutting speed, feed rate and heat treatment, as shown in figure 4. In particular, the surface roughness decreased with increasing cutting speed. Higher temperatures generated in the cutting zone because of increasing cutting speeds reduced the formation of BUE and friction at the tool–chip interface, which

shortened the tool–chip contact distance. Therefore, the surface roughness improved with increasing cutting speed. In addition, the lowest surface roughness values were obtained using CTT drills. This result can be attributed to the improved wear resistance conferred by the precipitation of additional carbide particles and the homogeneous distribution of carbides [3, 4, 12, 30]. This claim is supported by SEM images of cemented carbide drills, which are shown in figures 7–9. When we examined the effects of the feed rate on the surface roughness and thrust force, the surface roughness and thrust force values significantly increased with increasing feed rate. Because the vibrations during machining increase at higher feed rates because of the increased drilling thrust forces, the surface texture of the workpiece material deteriorates [3, 15, 16, 31]. The results of the force experiments confirmed this case. Figure 6 illustrates the thrust force values. The trend lines in figure 5 (surface roughness) and figure 6 (thrust force) are notably similar. An increase in the cutting speed decreased the thrust forces. This result can be attributed to the easy deformation of the workpiece material because thermal softening occurred with higher temperatures in the cutting zone [32]. Similarly, optimal values of the thrust force were obtained using the CTT drills. Because improvements in their micro-structures increased the wear resistance of the cemented carbide drills after the cryo-tempering process, the thrust force decreased. Maximal thrust forces were obtained with higher

Figure 5. Surface roughness values at 0.063 mm/rev and 60 m/min.

Figure 6. Thrust force values at 0.063 mm/rev and 60 m/min.

Figure 7. SEM pictures that show the wear types on the carbide drills after 300 drillings: (a) U, (b) CT and (c) CTT. (1) Fracture, (2) margin wear, (3) corner wear, (4) chisel edge wear, (5) chipping, (6) BUE and (7) flank wear.

Figure 8. SEM pictures that show the wear types on the carbide drills after 400 drillings: (a) U, (b) CT and (c) CTT. (1) Fracture, (2) margin wear, (3) corner wear, (4) chisel edge wear, (5) chipping, (6) BUE and (7) flank wear.

feed rates because of the rapid plastic deformation and increasing chip section and vibrations [33, 34].

In addition, a number of wear experiments were conducted to support the experimental results of the surface roughness and thrust force. In the wear experiments, 300, 400 and 500 holes were drilled on cold-work tool blocks, and the SEM images in figures 7–9 show the tips of three

different drills after the experiments. As shown in the SEM images, minimal amounts of all wear types were observed on the CTT drills. For example, the CTT drill exhibited less fracture and margin wear on the cutting edge than the U and CT drills. In addition, the amounts of corner wear, chipping, chisel edge wear and flank wear were notably low. This result can be explained by the positive effects of the

Figure 9. SEM pictures that show the wear types on the carbide drills after 500 drilling: (a) U, (b) CT and (c) CTT. (1) Fracture, (2) margin wear, (3) corner wear, (4) chisel edge wear, (5) chipping, (6) BUE and (7) flank wear.

cryo-tempering process, such as the formation of small carbide particles and the uniform and homogeneous distribution of those carbide particles [3, 4, 12].

6. Conclusions

In this study, the Taguchi technique was used to optimize the drilling parameters when drilling AISI D2 cold-work tool steel under dry cutting conditions. ANOVA was also used to evaluate the experimental results. The findings of this study are as follows.

- The optimal combination of the process parameters to obtain better surface roughness and thrust force was 0.063 mm/rev, 60 m/min and CTT drill (A_1 , B_3 , C_3).
- The experimental trials showed that the feed rate was the most influential factor, affecting both the surface roughness and the thrust force with percentage contributions of 66.97% and 80.07%, respectively.
- The confirmation experiments showed that both the surface roughness and the thrust force were predicted at (CI) of 95%.
- The CTT drills provided the lowest values of surface roughness and thrust force in comparison with the U and CT drills because of their improved wear resistance. The wear experiments verified this claim.

This study successfully employed the Taguchi technique to optimize the process parameters in the drilling process of cold-work tool steel to minimize the number of experiments. Further studies can consider more factors regarding the cryogenic treatment and the machinability of steels, such as different holding times, cryogenic temperatures, process parameters and cutting conditions.

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