



# A comparative study of multiple regression analysis and back propagation neural network approaches on plain carbon steel in submerged-arc welding

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**Abstract.** Weld bead plays an important role in determining the quality of welding particularly in high heat input processes. This research paper presents the development of multiple regression analysis (MRA) and artificial neural network (ANN) models to predict weld bead geometry and HAZ width in submerged arc welding process. Design of experiments is based on Taguchi's L16 orthogonal array by varying wire feed rate, transverse speed and stick out to develop a multiple regression model, which has been checked for adequacy and significance. Also, ANN model was accomplished with the back propagation approach in MATLAB program to predict bead geometry and HAZ width. Finally, the results of two prediction models were compared and analyzed. It is found that the error related to the prediction of bead geometry and HAZ width is smaller in ANN than MRA.

**Keywords.** Submerged arc welding (SAW); multi-regression analysis (MRA); artificial neural network (ANN); bead geometry and HAZ width.

## 1. Introduction

Submerged arc welding (SAW) is one of the most essential welding processes in manufacturing industries [1]. The weld bead plays an important role in determining the quality of the weld. Therefore, it is very important to set the proper welding process parameters to get the best bead geometry and HAZ width [2]. In SAW the weld quality is mainly influenced by independent variables like wire feed rate ( $W_f$ ), electrode stick ( $S_o$ ) out and traverse speed ( $T_s$ ), and these are also represented the strength of weldment [3–6]. So, it is necessary to control these input parameters for quality welding. Yang *et al* [6] used a regression model to control the process parameters of SAW. Raveendra and Parmaris [7] applied regression analysis to predict the welding geometry. Sen *et al* [8] developed a mathematical model by using a multiple linear regression analysis in MINITAB 13.1 to predict the weld bead geometry for double pulse gas metal arc welding process. Rao *et al* [9] developed a mathematical model based on multiple regression analysis (MRA) to correlate the welding process

parameters and weld bead geometry and prediction of bead geometry in pulsed GMA welding.

But most of the industrial processes are non-linear, complex, and the linear mathematical models are not giving a closer approach to describe the behavior of the processes. Recently, for observing and controlling the welding processes parameters many artificial intelligence (AI) methods or technique such as fuzzy logic (FL), artificial neural networks (ANN) [10–13], artificial neural fuzzy interface system (ANFIS) [14] and expert system have been deployed as key techniques. Many researchers (Ghosh *et al* [15], Li *et al* [16]) advocating the advantages of the above-mentioned models consideration of simplicity, applicability, powerful tools are reviewed. Nagesh and Datta [17] reported that artificial networks are powerful tools for analysis and modeling. An ANN model has been developed to establish the relationship between the welding process parameters and the weld bead geometry in laser welding [18], GMAW [19]. To predict and optimize the depth of penetration in hybrid CO<sub>2</sub> laser–MIG welding, an artificial neural network was used for 5005 Al–Mg alloy [20]. Dhas and Kumanan [21] present the development of Neuro hybrid model (NHM) to predict weld bead width in SAW.

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A comparison of multiple regression analysis (MRA) with artificial neuron network (ANN) was used as methods of predicting the bead geometry and mechanical properties [22–30]. In 2014, Xiong *et al* [31] reported that the neural network model has a better performance than regression model for predicting the bead geometry in GMAW process. Kim *et al* [32] studied the back propagation neural network (BPNN) considerably more accurate than multiple regressions (MRA) in modeling bead height in metal arc welding. Moreover, the prediction with ANN is more accurate than that with a regression equation [33].

Based on above trend, the main objective of this study is to develop an MRA and ANN models and techniques for predicting the weld bead geometry and HAZ width by a SAW for a given set of welding parameters. Finally, the results by the two prediction models were compared and analyzed.

## 2. Experiment design and procedure

In the experiment, AISI 1015 mild steel plates of sizes 200 mm × 100 mm × 12 mm and 3.15 mm diameter mild steel electrode coated with copper were used. Table 1 shows the chemical composition of the experimental plates and electrode wire. Welding is completed by depositing bead on plate in SAW machine (ADOR WELDING LTD. INDIA, Machine No: MODEL PS-1200 (F)) as shown in figure 1. The variations of the input parameters are done as per design matrix, keeping the voltage constant. As the voltage change in the actual welding is minimum and also not controllable as per design of the power source. So, as input variables it is not included in the present study. However, its value is recorded by induction type multimeter putting on the cable. Flux used in this experiment is fused type silicon product



**Figure 1.** SAW machine [the wire feed = 50 to 450 cm/min, welding speed = 0 to 150 cm/min and voltage = 415 V (max.)].

**Table 1.** Chemical composition (wt%) of the base plate and electrode wire.

Element	Carbon	Manganese	Silicon	Phosphorus	Sulphur	Carbon <sub>equ</sub>
Base metal	0.163	0.419	0.150	0.0190	0.0130	0.240
Electrode	0.040	0.40	0.050	–	–	–

**Table 2.** Chemical composition of flux.

Element	Al <sub>2</sub> O <sub>3</sub> + MnO <sub>2</sub>	CaO + MgO	SiO <sub>2</sub> + TiO <sub>2</sub>	CaF <sub>2</sub>
Wt%	35%	25%	20%	15%

with grain size 0.2–1.6 mm with basicity index 1.6 and the chemical composition is given in table 2.

## 3. Plan of investigation

The present work was planned to be carried out in the following steps:

- Identifying the important process parameters and finding their limits.
- Developing the design matrix and conducting the experiments.
- Recording the response variables such as penetration (P), bead width (W), reinforcement (R), and HAZ width.
- Developing mathematical models by MRA method.
- Calculating the regression co-efficient.
- Improvement of final mathematical model.
- Predicted the bead geometry shape and size by ANN model
- Comparison of MRA and ANN model.
- Analysis of results.

### 3.1 Selection of process parameters and their working ranges

Based on the effect on weld bead geometry, ease of control and capability of being maintained at the desired level, three independently controllable process parameters were identified to enable the carrying out of experimental work and developing the mathematical model. These are wire feed rate ( $W_f$ ), stick out or nozzle to plate distance ( $S_o$ ), traverse speed ( $T_s$ ) and their upper and lower limits together with notations and units are given in table 3.

### 3.2 Developing the design matrix and conducting the experiments as per the design matrix

In the present study, since three factors, each with four levels was selected as controllable process parameters

**Table 3.** Welding process control parameters and their levels.

Parameters	Units	Notation	Level 1	Level 2	Level 3	Level 4
Wire feed rate	mm/min	$W_f$	105	140	175	210
Stick out	mm	$S_o$	15	20	25	30
Traverse speed	m/min	$T_s$	0.75	0.9	1.15	1.2

**Table 4.** Design matrix with code independent process variables.

Experimental no.	Coded variable			Actual variable		
	Wire feed rate ( $W_f$ )	Stick out ( $S_o$ )	Traverse speed ( $T_s$ )	Wire feed rate ( $W_f$ )	Stick out ( $S_o$ )	Traverse speed ( $T_s$ )
1	1	1	1	105	15	0.75
2	1	2	2	105	20	0.9
3	1	3	3	105	25	1.15
4	1	4	4	105	30	1.2
5	2	1	2	140	15	0.9
6	2	2	1	140	20	0.75
7	2	3	4	140	25	1.2
8	2	4	3	140	30	1.15
9	3	1	3	175	15	1.15
10	3	2	4	175	20	1.2
11	3	3	1	175	25	0.75
12	3	4	2	175	30	0.9
13	4	1	4	210	15	1.2
14	4	2	3	210	20	1.15
15	4	3	2	210	25	0.9
16	4	4	1	210	30	0.75

**Table 5.**  $L_{16}$  design matrix with the experiment values of bead penetration, bead width, reinforcement and HAZ width.

Experimental no.	$W_f$	$S_o$	$T_s$	Penetration (mm)	Bead width (mm)	Reinforcement (mm)	HAZ width (mm)
1	105	15	0.75	4.00	12.00	1.86	1.40
2	105	20	0.90	3.80	11.20	1.80	1.37
3	105	25	1.15	3.10	10.25	1.70	1.30
4	105	30	1.20	3.20	10.10	1.50	1.10
5	140	15	0.90	4.10	14.10	2.41	1.46
6	140	20	0.75	4.80	13.26	2.45	1.82
7	140	25	1.20	3.56	11.36	2.27	1.16
8	140	30	1.15	4.00	10.76	2.37	1.37
9	175	15	1.15	5.80	11.10	2.76	1.22
10	175	20	1.20	5.30	10.00	2.79	1.24
11	175	25	0.75	6.10	12.60	3.04	1.83
12	175	30	0.90	6.26	11.30	3.50	1.55
13	210	15	1.20	6.40	9.44	3.44	1.34
14	210	20	1.15	7.30	10.00	3.40	1.30
15	210	25	0.90	7.28	11.00	3.50	1.87
16	210	30	0.75	6.52	11.46	4.45	1.77

variables were selected for conducting the experiments. The design matrix comprises 16 experiments is used to study the entire welding parameter space when the Taguchi's  $L_{16}$  orthogonal array design matrix is used. Sixteen

sets of test plates were welded as per the design matrix by selecting trails at random. The experimental layout for the welding process parameters using the  $L_{16}$  orthogonal array design matrix is shown in table 4 and table 5.

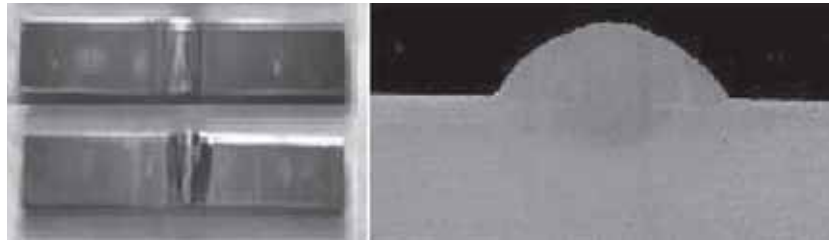


Figure 2. Image of welded samples.

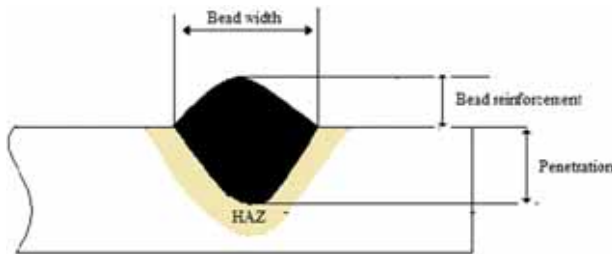


Figure 3. Weld bead geometry.

### 3.3 Recording the response parameters

Once the welding is over, all welded plates were cut approximately 100 mm long  $\times$  10 mm wide, transverse to the welding direction using a Buehler Abrasimet abrasive Cutter which included the bead shape and size, the heat affected zone and the base metal. After cutting, the samples were polished by different emery papers in 150, 400, 600, 1000, 1200, 1500 and up to 2000 grit papers as per ASTM E3. Then prepared samples are etchant with 2% Nital solution. Then the specimens are observed through low magnification microscope attached with the micro hardness tester (Vicker's Micro hardness test machine, Model: HV-10) and the scale is used to find the dimension of various parameters of bead geometry and HAZ width. Figure 2 and figure 3 are showing the typical welded samples and weld bead geometry respectively. The average values of weld penetration (P), width (W) and reinforcement (R) and HAZ width (from the two specimens for the same welding condition) were taken for each experiment. The dimensions of weld bead geometry of each welding condition are provided in table 5.

### 3.4 Development of mathematical models

An MRA was carried out for better understanding of the effects of the input variables on the output variables and a linear regression equation is also deduced for the prediction of the output variables. So, a mathematical model can be developed for predicting and to establish the interrelationship between welding process parameters to weld geometry and HAZ width by MRA. The general response function representing any of the weld-bead dimensions can be expressed as

$$Y = f(W_f, S_o, T_s) \quad (1)$$

$$Y = b_0 + b_1 W_f + b_2 S_o + b_3 T_s \quad (2)$$

where  $Y$  is the depended variables or response variables such as penetration, bead width, reinforcement and HAZ width;  $b_0$ ,  $b_1$ ,  $b_2$  and  $b_3$  is the coefficient.

### 3.5 Estimation of coefficients of the model

The values of the regression coefficients of the above polynomial were calculated with the help of Minitab statistical software. The estimated regression coefficients are given in table 6. The value of regression co-efficient gives an idea as to what extent the process parameter variables affect the response parameters. Higher values of regression co-efficient signify high influence of input variables on the response parameters and inversely relationship is found for the value of regression co-efficient which is negative.

### 3.6 Testing the significance of regression coefficients

The value of the regression coefficients gives an idea as to what extent the control variables affect the output or response variables. The less significant coefficients can be dropped along with the responses with which they are related, without sacrificing accuracy. To achieve this,  $p$  value is used. According to this test when the calculated value of  $p < 0.05$  for the desired level of probability (say 95%), the regression coefficient becomes significant (table 7). These conditions were satisfied for the development of final mathematical model.

### 3.7 Development of final mathematical model

The significant regression coefficients, thus selected were recalculated and final models were developed using only these coefficients. The final mathematical model is used to predict the weld bead geometry and HAZ width by substituting the above significant coefficient values in Eq. (2). This is done as per design table in coded form of the

**Table 6.** Estimated regression coefficients of mathematical model for bead geometry parameters and HAZ width.

Coefficients	Penetration (p)	Bead width (W)	Reinforcement (R)	HAZ width
$b_0$	2.8825	14.2513	1.36375	1.63125
$b_1$	1.1985	-0.3408	0.64825	0.08225
$b_2$	-0.0725	-0.0428	0.06925	0.03525
$b_3$	-0.2595	-0.8737	-0.17075	-0.18775

**Table 7.** ANOVA analysis for bead geometry and HAZ width.

Response parameter	Source	Sum of squares	Degree of freedom	Adj. mean- squares	F-value	p-value
P	Regression	30.1800	6	10.0600	39.95	0.000
	Residual error	3.02200	9	0.25200		
W	Regression	27.2060	6	3.02289	7.11	0.013
	Residual error	2.54950	9	0.42491		
R	Regression	9.55748	6	1.06194	23.39	0.001
	Residual error	0.27241	9	0.04540		
HAZ width	Regression	1.01480	6	0.11275	6.70	0.016
	Residual error	0.10100	9	0.01683		

independent variables. Finally, based upon regression analysis the following linear equations are developed and proposed as follows:

$$P = 2.88 + 1.20W_f - 0.259T_s \quad (3)$$

$$W = 14.8 - 0.964T_s \quad (4)$$

$$R = 1.36 + 0.648W_f - 0.171T_s \quad (5)$$

$$HAZ\ width = 1.63 + 0.0822W_f - 0.188T_s \quad (6)$$

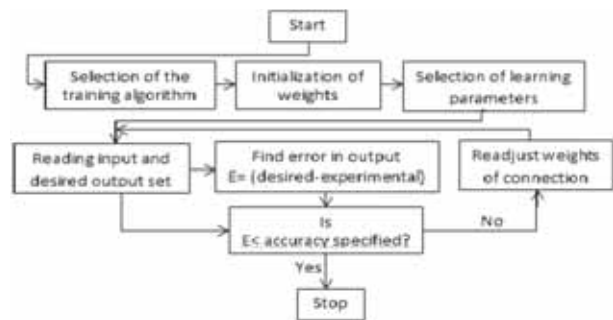
#### 4. Methodology of artificial neural network modeling

The arrangement of neurons into layer and the connection pattern within and between the layers are called as network architecture. The architecture consists of three parts

1. Input layer receives the welding parameters
2. Hidden layer
3. Output layer obtaining the predicted values of response parameters.

The performance of the neural networks depends upon, the number of hidden layers and number of neurons in the hidden layers. It was trained to help of back propagation (BP) algorithm in MATLAB. The flow chart for the back propagation algorithm is shown in figure 4.

In training, it is essential to balance the importance of each parameter, the data must be normalized. Since, neural networks works better in the range of 0 to 1, the input and output vector values are converted in the range of 0 to 1 using the following equation.



**Figure 4.** Flow chart for neural network.

$$X_n = (X - X_{min}) / (X_{max} - X_{min}) \quad (7)$$

where  $X_n$  = normalized value,  $X$  = actual input (or output) value,  $X_{max}$  = Maximum value of the inputs (or outputs),  $X_{min}$  = Minimum value of the inputs (or outputs)

The designed neural network structure was 3-5-4 (3 neurons in input layer, 5 neurons in hidden layer and 4 neurons in output layer). Many different ANN network algorithms have been proposed in welding process, but back propagation (BP) algorithm has been found to be the best for prediction [12]. And proposed back propagation neural network architecture is shown in figure 5.

#### 5. Results and discussion

Multiple linear regression analysis is one of the most widely used methodologies for expressing the dependence of response parameters on several independent input



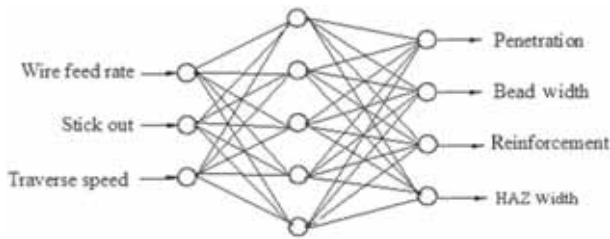


Figure 5. Back propagation neural network architecture.

Table 8. ANOVA results for mathematical model validation.

Response parameter	R-Square (%)	Adjusted R-square (%)
P	94.40	86.00
W	91.43	78.58
R	97.23	93.07
HAZ width	90.95	77.37

parameters. At first the analysis of variance (ANOVA) of the regression model is considered for the significance and also considered for finding the correlation among the variables for the better accuracy of the statistical model. The experimental data were used to develop linear models, and analysis of the models was carried out through ANOVA (table 7). Above all the final mathematical model equation is validated by  $R^2$ -value (94.4%, 91.43%, 97.23% and 90.95%) (table 8). The Adjusted  $R^2$ -value statistic compensates for the number of variables in the model and it will only increase if added variables contribute significantly to the model. The adjusted  $R^2$ -value suggests the strength of the model. The Adjusted  $R^2$ -value statistic in the model for penetration, bead width, reinforcement and HAZ width are nearly 80% (table 8). It means that 80% of the variation in the bead geometry shape and size can be attributed to these three variables (wire feed rate, transverse speed and stick out) which ultimately suggest the good explanatory power of the regression equation.

A multi regression equation (i.e., Eqs. 3–6) was used to predict the weld bead geometry and HAZ width. The

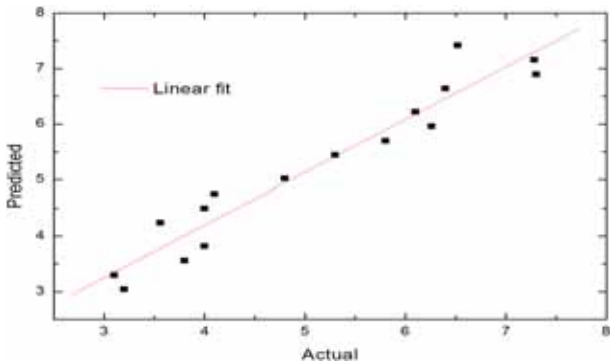


Figure 6. Scatter diagram for penetration.

validity of the above equations can be judged from their coefficients of correlation and also from scatter-diagrams (figures 6, 7, 8, 9), which indicated that, a good relationship between the actual and predicted values of bead geometry and HAZ width exists. After that the value of various

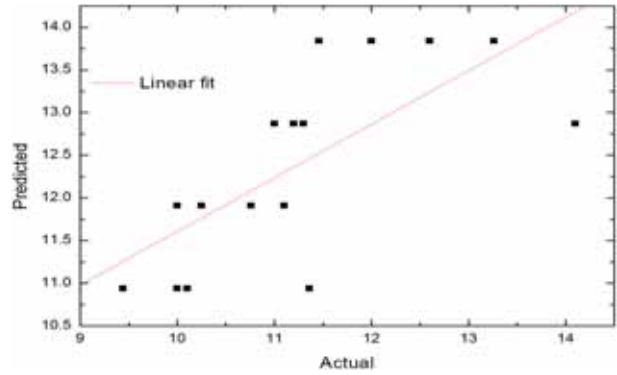


Figure 7. Scatter diagram for bead width.

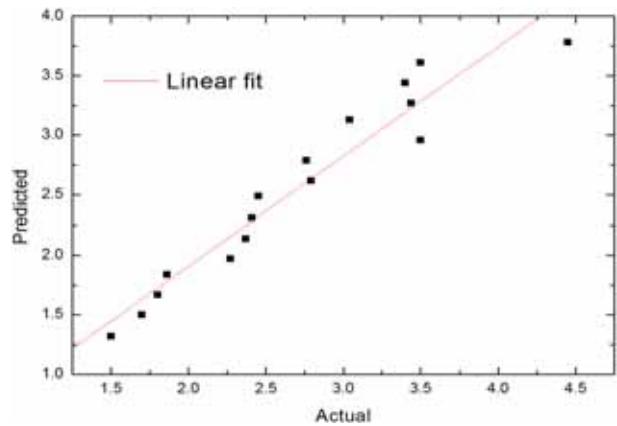


Figure 8. Scatter diagram for reinforcement.

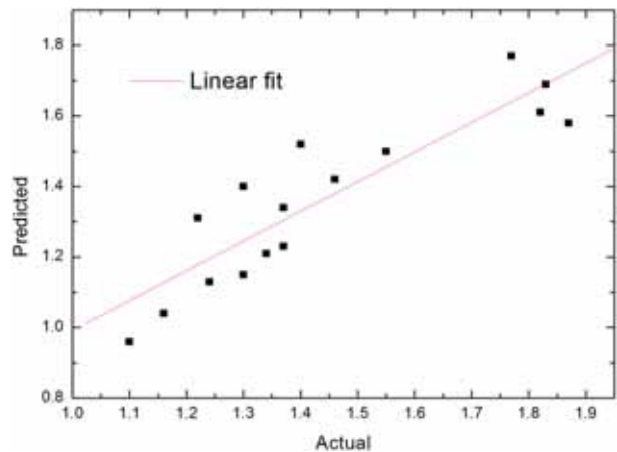
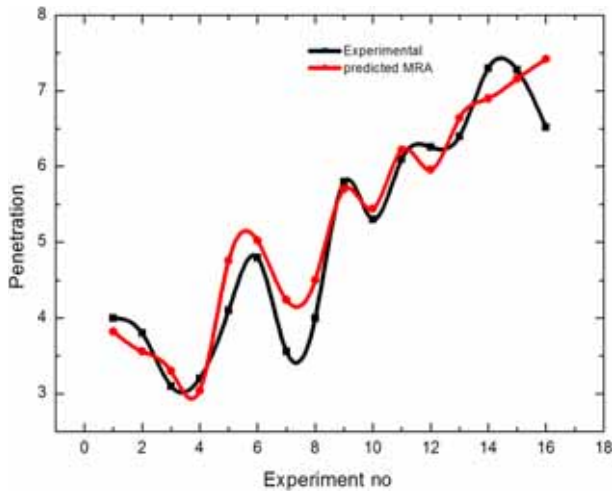


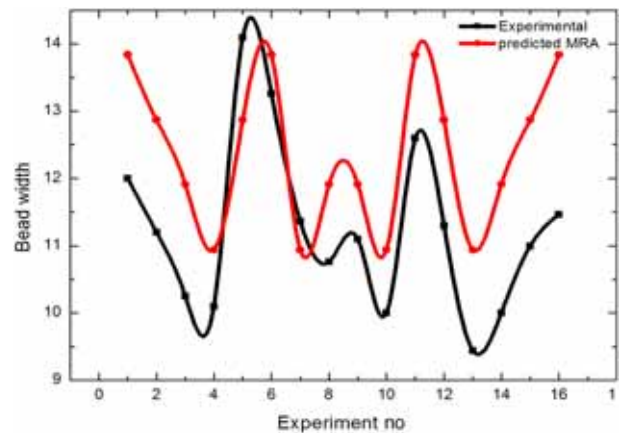
Figure 9. Scatter diagram for HAZ width.

**Table 9.** Comparison of actual and predicted values of the bead geometry and HAZ width for MRA and ANN model.

Sl. no	P	W	R	HAZ width	MRA predicted value				ANN predicted value			
					P	W	R	HAZ width	P	W	R	HAZ width
1	4.00	12.00	1.86	1.40	3.82	13.84	1.84	1.52	3.99	12.00	1.85	1.39
2	3.80	11.20	1.80	1.37	3.56	12.87	1.67	1.34	3.79	11.20	1.80	1.36
3	3.10	10.25	1.70	1.30	3.30	11.91	1.50	1.15	3.14	10.19	1.71	1.29
4	3.20	10.10	1.50	1.10	3.04	10.94	1.32	0.96	3.15	10.15	1.49	1.1
5	4.10	14.10	2.41	1.46	4.76	12.87	2.31	1.42	3.86	14.09	2.84	1.46
6	4.80	13.26	2.45	1.82	5.02	13.84	2.49	1.61	4.79	13.26	2.44	1.98
7	3.56	11.36	2.27	1.16	4.24	10.94	1.97	1.04	3.55	11.36	2.25	1.16
8	4.00	10.76	2.37	1.37	4.50	11.91	2.14	1.23	3.50	10.75	2.38	1.36
9	5.80	11.10	2.76	1.22	5.70	11.91	2.79	1.31	5.79	10.50	2.77	1.22
10	5.30	10.00	2.79	1.24	5.44	10.94	2.62	1.13	5.29	9.9	2.77	1.24
11	6.10	12.60	3.04	1.83	6.22	13.84	3.13	1.69	6.10	12.59	3.04	1.83
12	6.26	11.30	3.50	1.55	5.96	12.87	2.96	1.50	6.26	11.29	3.50	1.55
13	6.40	9.44	3.44	1.34	6.64	10.94	3.27	1.21	6.40	8.44	3.42	1.33
14	7.30	10.00	3.40	1.30	6.90	11.91	3.44	1.40	7.29	9.99	3.40	1.29
15	7.28	11.00	3.50	1.87	7.16	12.87	3.61	1.58	7.28	11.00	3.50	1.89
16	6.52	11.46	4.45	1.77	7.42	13.84	3.78	1.77	6.51	11.45	4.44	1.77



**Figure 10.** Actual and predicted penetration using MRA model.



**Figure 11.** Actual and predicted bead width using MRA model.

parameters of bead geometry and HAZ width is calculated based upon above linear equation of the regression model and presented in table 9. The results of the experimental values and predicted values are compared and the related graphs are shown in figures 10, 11, 12 and 13. From the graphs, it is observed that the weld bead geometry and HAZ width are in good agreement except for a few combinations of parameters. Similarly the result obtained from ANN model is also provided in table 9.

Figures 14, 15, 16 and 17 show that the relationship between the experimental and predicted values of bead geometry and HAZ width in the artificial neural network. It

can be seen from figures; the experimental and predicted values of bead geometry shape and size are too close to each other.

Further, a comparison of MRA and ANN was done to see the efficiency of a particular model. In this respect comparison graphs of predicted values of bead geometry and HAZ width are in figures 18, 19, 20 and 21. From this comparison it appears that ANN is better model comparable to MRA for predicting bead geometry and HAZ width. As the ANN model is based on non-linear concept comparable to MRA which is based on linear concept, the prediction is more accurate. However, the variation of the result based upon the above two models are within  $\pm 20\%$  (table 10).

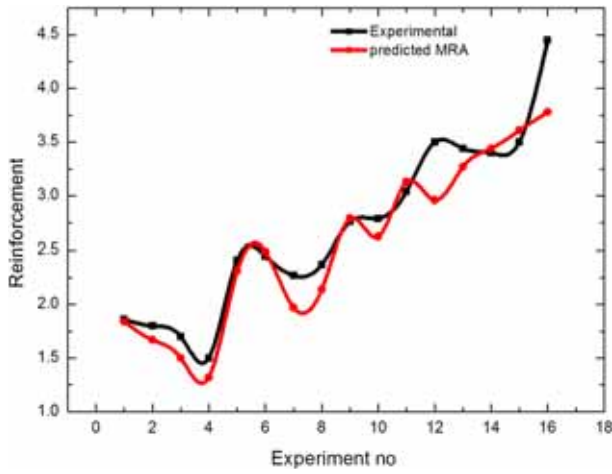


Figure 12. Actual and predicted reinforcement using MRA.

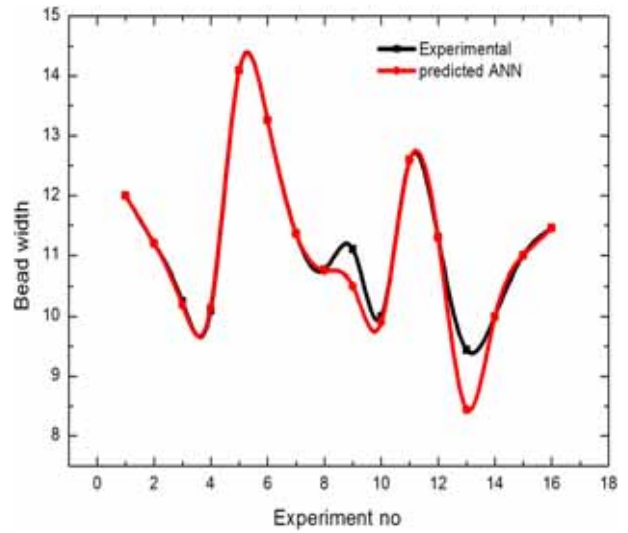


Figure 15. Actual and predicted bead width using ANN model.

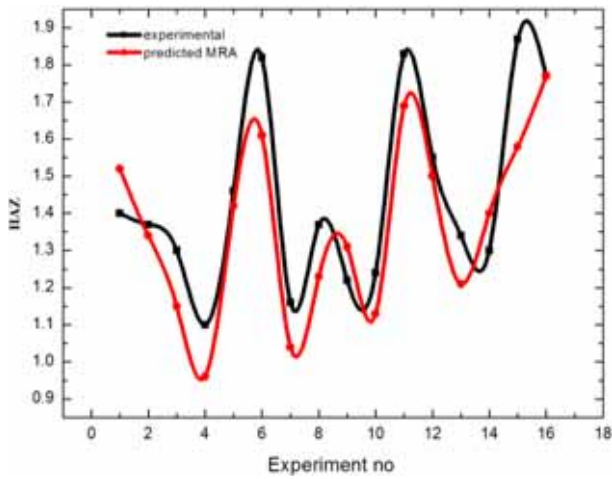


Figure 13. Actual and predicted HAZ width using MRA model.

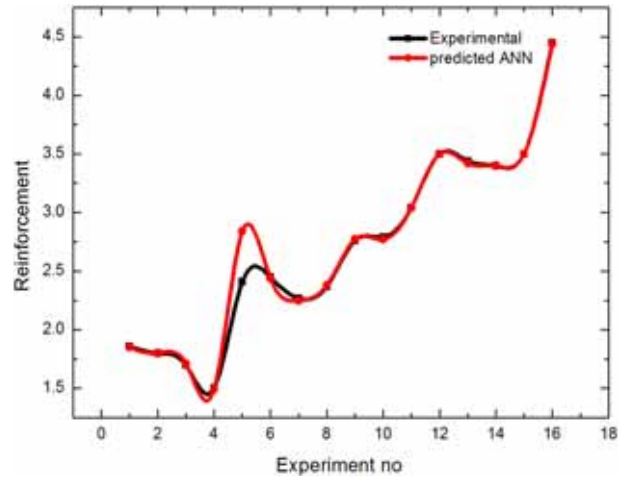


Figure 16. Actual and predicted reinforcement using ANN model.

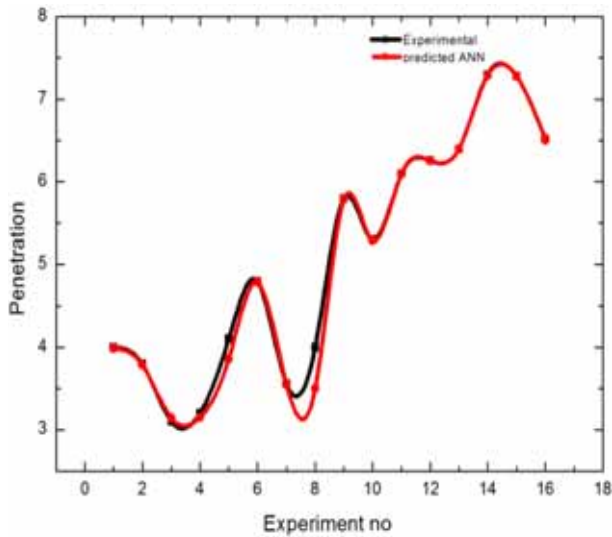


Figure 14. Actual and predicted penetration using ANN model.

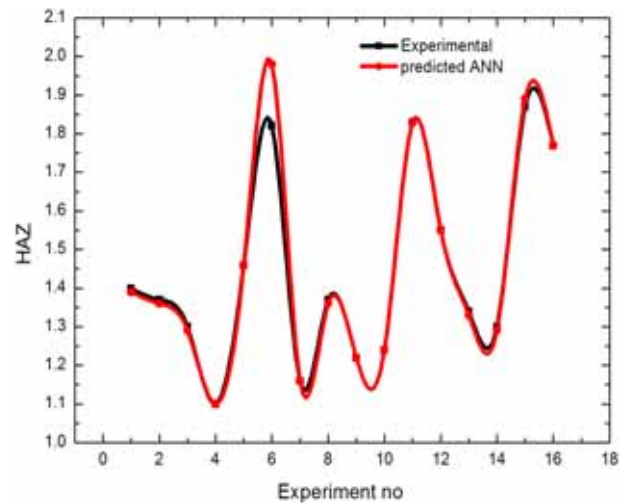


Figure 17. Actual and predicted HAZ width using ANN model.



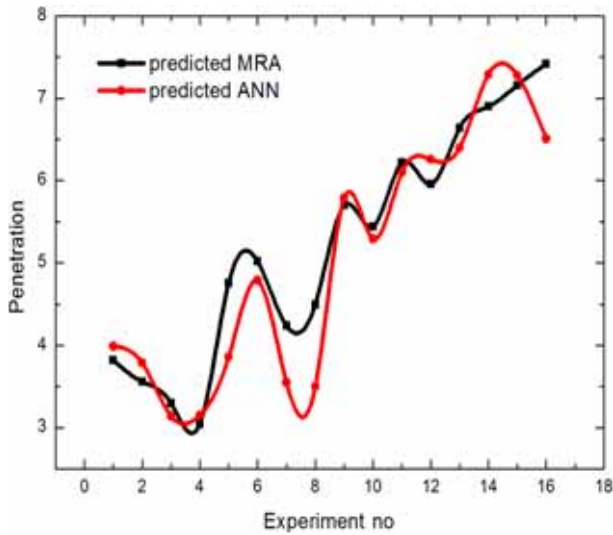


Figure 18. Predicted penetration using ANN and MRA.

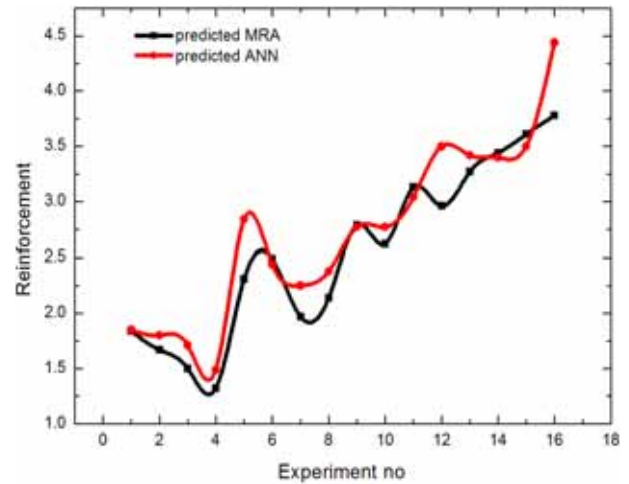


Figure 20. Predicted reinforcement using ANN and MRA.

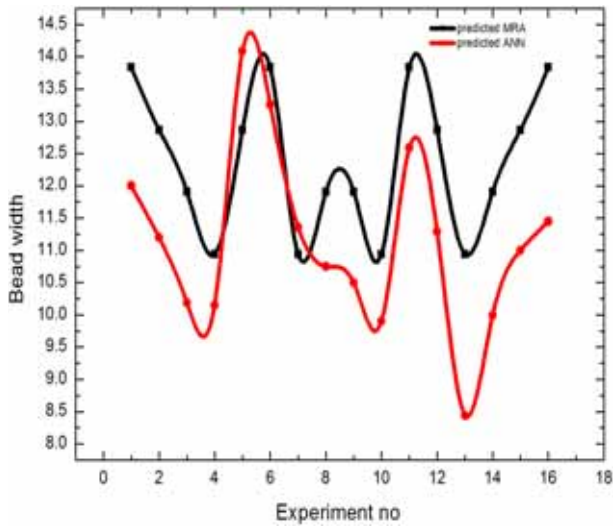


Figure 19. Predicted bead width using ANN and MRA.

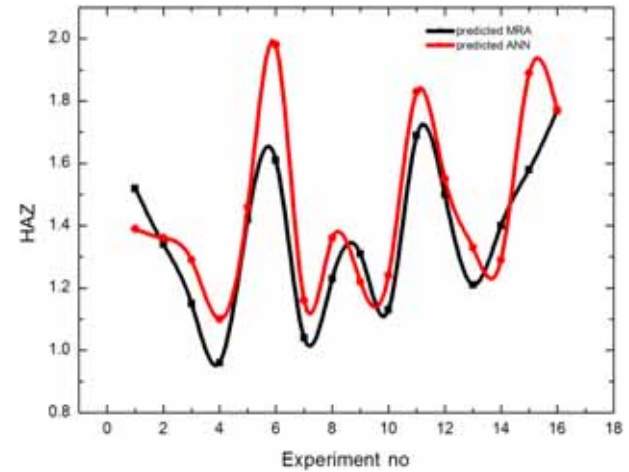


Figure 21. Predicted HAZ width using ANN and MRA.

## 6. Conclusion

Based on the different welding parameters ranges (wire feed rate is 105–210 mm/min; transverse speed is 0.75–1.2 mm/min; stick out is 15–25 mm), the MRA and ANN are used to predict the bead geometry and HAZ width in present study and the following conclusions were drawn through comparison and analysis.

1. There is a linear relationship consequent between the welding process parameters and the weld bead geometry

and HAZ width in linear equations through the multiple regression analysis.

2. Developed linear equations through MRA may be used to predict the various components of weld bead geometry and HAZ width in the welding of mild steel plates by SAW process.
3. The best architecture found by using back-propagation algorithm is 3-5-4 for the present work.
4. In ANN model, the percentage errors obtained for bead geometry and HAZ width are very low. It proves that the Back Propagation ANN model developed in this study is capable of predicting weld bead geometry and HAZ width with acceptable accuracy.

**Table 10.** Comparison of percentage error of predicted and actual values for MRA and ANN model.

Sl no.	% Error for MRA				% Error for ANN			
	P	W	R	HAZ width	P	W	R	HAZ width
1	4.71	-13.2	1.08	-7.89	0.25	0.00	0.53	0.72
2	6.74	-12.9	7.78	2.23	0.26	0.00	0.00	0.73
3	-6.06	-13.9	13.3	13.04	-1.29	0.58	-0.58	0.77
4	5.26	-7.67	13.6	14.5	1.56	-0.49	0.66	0.00
5	-13.8	9.55	4.32	2.81	0.00	0.07	0.69	0.00
6	-4.38	-4.19	-1.60	13.1	0.20	0.00	0.41	0.00
7	-16.0	3.83	15.2	11.5	0.28	0.00	0.88	0.00
8	-11.1	-9.65	10.7	11.3	0.00	0.09	-0.42	0.73
9	1.75	-16.8	-1.07	-6.87	0.17	0.00	-0.36	0.00
10	-2.57	-8.59	6.48	9.73	0.18	1.00	0.72	0.00
11	-1.92	-8.95	-2.87	8.28	0.00	0.07	0.00	0.00
12	5.03	-12.1	18.2	3.34	0.00	0.08	0.00	0.00
13	-3.61	-13.7	5.19	10.7	0.00	0.00	0.58	0.75
14	5.79	-16.0	-1.16	-7.14	0.13	0.11	0.00	0.77
15	1.67	-14.5	-3.04	18.3	0.00	0.00	0.00	0.53
16	-12.1	-17.1	17.7	0.00	0.15	0.08	0.23	0.00

5. The prediction accuracy is better in ANN than MRA model and the variation of the result based upon the two models are within  $\pm 20\%$ .

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