

## Inverse transient thermoelastic deformations in thin circular plates

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**Abstract.** This paper deals with the determination of unknown heating temperatures and temperature distributions on the upper surface of a thin circular plate, defined as  $0 \leq r \leq a$ ,  $-b/2 \leq z \leq b/2$ . The expressions of unknown heating temperatures and temperature distributions are obtained in series form, involving Bessel's functions with the help of the integral transform technique. Thermoelastic deformations are discussed with the help of temperature and are illustrated numerically.

**Keywords.** Inverse transient; thermoelastic deformation

### 1. Introduction

The inverse thermoelastic problem consists of determination of the temperature, the heat flux on the boundary surfaces of the solid when the conditions of the displacement and stresses are known at some points of the solid under consideration. Grysa & Cialkowski (1980), Grysa & Kozłowski (1982) investigated one-dimensional transient thermoelastic problems and derived the heating temperature and heat flux on the surface of an isotropic infinite slab. The problems of normal deflection of an axisymmetrically heated circular plate in the case of fixed and simply supported edges have been considered by Boley & Weiner (1960). Further, Roychoudhuri (1973) has succeeded in determining the normal deflection of a thin clamped circular plate due to ramp-type heating of a concentric circular region of the upper face. Ishihara & Noda (1997) has considered the theoretical analysis of thermoelastoplastic deformation of a circular plate due to partially distributed heat supply. In this paper, we modify the work of Roychoudhuri (1973) and discuss the thermoelastic deformation on the upper surface in a thin circular plate subjected to heating. The results, obtained in series form involving Bessel's functions, are illustrated numerically.

## 2. Analysis

### 2.1 Inverse transient heat conduction problem

Consider a thin circular plate of radius  $a$  and thickness  $b$  defined as  $0 \leq r \leq a$ ,  $-b/2 \leq z \leq b/2$ . The plate is initially at zero temperature.

The temperature  $T(r, z, t)$  of the plate at time  $t$ , satisfying the heat conduction equation is as

$$\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2} = \frac{1}{k} \frac{\partial T}{\partial t}, \quad (1)$$

with the initial condition, boundary conditions and interior condition respectively, as

$$t = 0, \quad T(r, z, t) = 0, \quad (2)$$

$$r = a, \quad [(\partial T / \partial r) + h_e T] = 0, \quad (3)$$

$$z = -b/2, \quad [(\partial T / \partial z) - h_{s_1} T] = g(r, t) \text{ (unknown)}, \quad (4)$$

$$z = b/2, \quad [(\partial T / \partial z) + h_{s_2} T] = 0, \quad (5)$$

$$\text{and } z = \xi, T(r, z, t) = f(r, t) \text{ (known)}. \quad (6)$$

where  $-(b/2) < \xi < (b/2)$ ,  $k$  is thermal diffusivity of the material of the plate and  $h_{s_1}$ ,  $h_{s_2}$  and  $h_e$  are the relative heat transfer coefficients of the plate on the upper surface ( $z = -b/2$ ), lower surface ( $z = b/2$ ) and outer curved surface ( $r = a$ ) respectively.

Equations (1) to (6) constitute the mathematical formulation of the inverse heat conduction problem.

### 2.2 Thermoelastic problem

In this subsection, we formulate the thermoelastic behaviour of a circular plate. We assume that the plate is sufficiently thin. Therefore, we can introduce the assumption that the plane perpendicular to the neutral plane ( $z = 0$ ) before deformation remains the plane perpendicular to it after deformation, and that the axial stress  $\sigma_{zz}$  is negligible compared to the other stress components. Furthermore  $\sigma_{r\theta}$ ,  $\sigma_{\theta z}$ ,  $\epsilon_{r\theta}$  and  $\epsilon_{\theta z}$  are all zero because the plate deforms axisymmetrically, where  $\epsilon_{r\theta} = (\sigma_{r\theta}/2G)$  and  $\epsilon_{\theta z} = (\sigma_{\theta z}/2G)$ , and  $G$  is the shear modulus.

The differential equation satisfied by force function  $F$  is defined (Ishiharar Noda 1997) as

$$\frac{d}{dr}(\nabla^2 F) = -\frac{d}{dr} N_T, \quad (7)$$

where

$$\nabla^2 = \left( \frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right),$$

and the thermal resultant force,  $N_T$ , is defined as

$$N_T = \int_{-b/2}^{b/2} \alpha E T \, dz, \quad (8)$$

where  $\alpha$  and  $E$  are the coefficient of linear thermal expansion and Young's modulus respectively.

The boundary condition concerning the in-plane deformation is given by

$$r = a, \quad dF/dr = 0, \quad F = 0. \quad (9)$$

The differential equation satisfied by the deflection  $\omega(r, t)$  is

$$D \frac{d}{dr} (\nabla^2 \omega) = - \frac{1}{(1-\nu)} \frac{d}{dr} M_T, \quad (10)$$

where  $D$  is the flexural rigidity of the plate denoted by

$$D = \frac{Eb^3}{12(1-\nu^2)}, \quad (11)$$

and the resultant thermal moment  $M_T$  is defined as

$$M_T = \int_{-b/2}^{b/2} E\alpha T z dz. \quad (12)$$

The boundary conditions concerning the out-of-plane deformation are

$$\left. \begin{array}{l} r = a, M_r = 0 \\ \text{and } r = 0, \omega = 0 \end{array} \right\} \quad (13)$$

where

$$M_r = D \left( \frac{d^2 \omega}{dr^2} + \frac{\nu}{r} \frac{d\omega}{dr} \right) + \frac{M_T}{1-\nu} = 0.$$

Equations (7) to (13) constitute the mathematical formulation of the thermoelastic problem.

### 3. Solution of the inverse heat conduction problem

#### 3.1 Determination of the temperature function, $T(r, z, t)$ and unknown heating temperature, $g(r, t)$

On applying the finite Hankel transform and Laplace transform to (1) to (6) and then obtaining the inverses of the resultant equations, we obtain the expressions for temperature distribution and unknown heating temperature respectively, as

$$\begin{aligned} T(r, z, t) = & \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_{mn}(\xi_n, \lambda_m) \cdot \phi_m(n, t) \cdot J_0(\xi_n r) \\ & \times \left[ -\lambda_m \cos \left( \frac{\lambda_m}{\xi - (b/2)} \cdot (z - (b/2)) \right) \right. \\ & \left. + h_{s1} \left( \xi - \frac{b}{2} \right) \sin \left( \frac{\lambda_m}{\xi - (b/2)} (z - (b/2)) \right) \right] \quad (14) \end{aligned}$$

and

$$g(r, t) = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} B_{mn}(\xi_n, \lambda_m) \cdot \phi_m(n, t) \cdot J_0(\xi_n r), \quad (15)$$

where

$$A_{mn}(\xi_n, \lambda_m) = \frac{-4K}{(\xi - (b/2))^2} \left[ \frac{\lambda_m}{a^2 \{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \}} \right] \\ \times \left[ \frac{1}{\lambda_m \sin(\lambda_m) + [h_{s_2}(\xi - (b/2)) - 1] \cos(\lambda_m)} \right], \quad (16)$$

$$B_{mn}(\xi_n, \lambda_m) = \frac{-4K}{(\xi - (b/2))^3} \left[ \frac{\lambda_m}{a^2 \{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \}} \right] \\ \times \frac{[-\lambda_m^2 + h_{s_1} h_{s_2} (\xi - (b/2))^2] \sin(\lambda_m b / [\xi - (b/2)]) \\ + \lambda_m (\xi - (b/2)) (h_{s_1} + h_{s_2}) \cos(\lambda_m b / [\xi - (b/2)])}{\lambda_m \sin(\lambda_m) + [h_{s_2}(\xi - (b/2)) - 1] \cos(\lambda_m)} \quad (17)$$

and

$$\phi_m(n, t) = \int_0^t \bar{f}(\xi_n, \tau) \cdot \exp \left\{ -K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) (t - \tau) \right\} d\tau, \quad (18)$$

where  $m, n$  are positive integers,  $\xi_n$  is the  $n$ th positive root of the transcendental equation

$$-\xi J_1(\xi a) + h_e J_0(\xi a) = 0,$$

and  $\lambda_m$  is the  $m$ th positive root of the transcendental equation

$$\lambda \cos(\lambda) - h_{s_2}(\xi - (b/2)) \sin(\lambda) = 0.$$

#### 4. Solution of the thermoelastic problem

##### 4.1 Determination of force component, $F(r, t)$

Substituting the value of temperature  $T(r, z, t)$  from (14) in (8), we obtain

$$N_T = -\alpha E \left( \xi - \frac{b}{2} \right)^2 \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{A_{mn}(\xi_n, \lambda_m)}{\lambda_m} \phi_m(n, t) \right. \\ \times \left\{ \left( \frac{\lambda_m}{(\xi - (b/2))} \right) \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right. \\ \left. \left. + h_{s_1} \left[ 1 - \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right\} J_0(\xi_n r) \right], \quad (19)$$

where  $A_{mn}(\xi_n, \lambda_m)$  and  $\phi_m(n, t)$  are as in (16) and (18) respectively.

On substituting (19) in (7) and using (9), we obtain force component  $F(r, t)$  as

$$\begin{aligned}
 F = \alpha E \left( \xi - \frac{b}{2} \right)^2 \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} & \left[ \frac{A_{mn}(\xi_n, \lambda_m)}{\lambda_m \xi_n} \phi_m(n, t) \right. \\
 & \times \left\{ \left( \frac{\lambda_m}{\xi - (b/2)} \right) \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) + h_{s1} \left[ 1 - \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right\} \\
 & \times \left[ J_0(\xi_n r) - J_0(\xi_n a) + \frac{\xi_n}{2a} (r^2 - a^2) J_1(\xi_n a) \right]. \quad (20)
 \end{aligned}$$

#### 4.2 Determination of deflection function, $\omega(r, t)$

On substituting the value of temperature  $T(r, z, t)$  from (14) in (12), we get

$$\begin{aligned}
 M_T = \alpha E \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} & \left[ A_{mn}(\xi_n, \lambda_m) \phi_m(n, t) \left\{ \frac{b}{2\lambda_m} \left( \xi - \frac{b}{2} \right) \right. \right. \\
 & \times \left[ \left( \frac{\lambda_m}{\xi - (b/2)} \right) \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) - h_{s1} \left[ 1 + \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right] \\
 & + \frac{\left( \xi - \frac{b}{2} \right)^2}{\lambda_m^2} \left[ \lambda_m \left( \cos \left( \frac{\lambda_m b}{\xi - b/2} \right) - 1 \right) \right. \\
 & \left. \left. + \left( \xi - \frac{b}{2} \right) h_{s1} \sin \left( \frac{\lambda_m b}{\xi - b/2} \right) \right] \right] J_0(\xi_n r). \quad (21)
 \end{aligned}$$

Finally, we substitute the value of  $M_T$  from (21) in (10) and use (13), and get deflection function  $\omega(r, t)$  as

$$\begin{aligned}
 \omega = \frac{\alpha E}{D(1-\nu)} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} & \left[ \frac{A_{mn}(\xi_n, \lambda_m)}{\xi_n} \phi_m(n, t) \left\{ \frac{b}{2\lambda_m} \left( \xi - \frac{b}{2} \right)^2 \right. \right. \\
 & \times \left[ \left( \frac{\lambda_m}{\xi - (b/2)} \right) \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) - h_{s1} \left[ 1 + \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right] \\
 & + \frac{\left( \xi - \frac{b}{2} \right)^2}{\lambda_m^2} \left[ \lambda_m \left( \cos \left( \frac{\lambda_m b}{\xi - b/2} \right) - 1 \right) \right. \\
 & \left. \left. + \left( \xi - \frac{b}{2} \right) h_{s1} \sin \left( \frac{\lambda_m b}{\xi - b/2} \right) \right] \right] \\
 & \times \left[ J_0(\xi_n r) - \frac{r^2 \xi_n}{2(1+\nu)} \left\{ (1 - \xi_n) J_0(\xi_n a) + \frac{(1-\nu)}{a} J_1(\xi_n a) \right\} - 1 \right], \quad (22)
 \end{aligned}$$

and the angle of variation with time as

$$\theta = -d\omega/dr,$$

i.e.

$$\begin{aligned} \theta = & \frac{\alpha E}{Da(1-\nu^2)} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ A_{mn}(\xi_n, \lambda_m) \phi_m(n, t) \left\{ \frac{b}{2\lambda_m} \left( \xi - \frac{b}{2} \right)^2 \right. \right. \\ & \times \left[ \left( \frac{\lambda_m}{\xi - (b/2)} \right) \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) - h_{s_1} \left[ 1 + \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right] \\ & + \frac{\left( \xi - \frac{b}{2} \right)^2}{\lambda_m^2} \left[ \lambda_m \left( \cos \left( \frac{\lambda_m b}{\xi - b/2} \right) - 1 \right) \right. \\ & \left. \left. + \left( \xi - \frac{b}{2} \right) h_{s_1} \sin \left( \frac{\lambda_m b}{\xi - b/2} \right) \right] \right\} \\ & \times [a(1+\nu)J_1(\xi_n r) + r\{a(1-\xi_n)J_0(\xi_n a) + (1-\nu)J_1(\xi_n a)\}]. \end{aligned} \tag{23}$$

**5. Special case**

Let

$$f(r, t) = (1 - e^{-At})(r^2 - a^2)^2, \tag{24}$$

where  $A > 0$  is constant.

We apply the finite Hankel transform defined as (Sneddon 1972) to get

$$\bar{f}(\xi_n, \tau) = \frac{a^2}{\xi_n^2} \left[ \left( \frac{64}{a\xi_n^3} - \frac{8a}{\xi_n} \right) J_1(\xi_n a) - \frac{32}{\xi_n^2} J_0(\xi_n a) \right] (1 - e^{-A\tau}). \tag{25}$$

On using (25) in (18), we obtain

$$\begin{aligned} \phi_m(n, t) = & \frac{a^2}{\xi_n^2} \left[ \left( \frac{64}{a\xi_n^3} - \frac{8a}{\xi_n} \right) J_1(\xi_n a) - \frac{32}{\xi_n^2} J_0(\xi_n a) \right] \\ & \times \left[ \frac{1 - e^{-k\left(\xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2}\right) t}}{k\left(\xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2}\right)} + \frac{e^{-At} - e^{-k\left(\xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2}\right) t}}{A - k\left(\xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2}\right)} \right] \end{aligned} \tag{26}$$

Finally, substituting (26), (16), (17) in (14), (15), (20), (22) and (23), we obtain the expressions for temperature distribution, unknown heating temperature, force component, thermal deflection and angle of variation respectively, as

$$\begin{aligned} T(r, z, t) &= \frac{-4K}{(\xi - (b/2))^2} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{\lambda_m [((64/a\xi_n^3) - (8a/\xi_n)) J_1(\xi_n a) - (32/\xi_n^2) J_0(\xi_n a)]}{\xi_n^2 [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2} \right] J_0(\xi_n r) \end{aligned}$$

$$\begin{aligned} & \times \frac{-\lambda_m \cos \left[ \frac{\lambda_m}{(\xi - (b/2))} \left( z - \frac{b}{2} \right) \right] + h_{s_2} \left( \xi - \frac{b}{2} \right) \sin \left[ \frac{\lambda_m}{(\xi - (b/2))} \left( z - \frac{b}{2} \right) \right]}{\lambda_m \sin(\lambda_m) + [h_{s_2}(\xi - (b/2)) - 1] \cos(\lambda_m)} \\ & \times \frac{1 - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right]} + \frac{e^{-At} - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{A - K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right)}, \end{aligned} \tag{27}$$

$$\begin{aligned} g(r, t) &= \frac{-4K}{(\xi - (b/2))^3} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{\lambda_m [(64/a\xi_n^3) - (8a/\xi_n)] J_1(\xi_n a) - (32/\xi_n^2) J_0(\xi_n a)}{\xi_n^3 \{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \}} \right] J_0(\xi_n r) \\ & \times \frac{[-\lambda_m^2 + h_{s_1} h_{s_2} (\xi - (b/2))^2] \sin(\lambda_m b / (\xi - b/2)) + \lambda_m (\xi - (b/2)) (h_{s_1} + h_{s_2}) \cos(\lambda_m b / (\xi - b/2))}{\lambda_m \sin(\lambda_m) + [h_{s_2} (\xi - (b/2)) - 1] \cos(\lambda_m)} \\ & \times \frac{1 - \exp \left\{ -k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right] t \right\}}{k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right]} + \frac{\exp(-At) - \exp \left\{ -k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t \right\}}{A - K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right)}, \end{aligned} \tag{28}$$

$$\begin{aligned} F &= -4k\alpha E \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{[(64/a\xi_n^3) - (8a/\xi_n)] J_1(\xi_n a) - (32/\xi_n^2) J_0(\xi_n a)}{\xi_n^3 \{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \}} \right] \\ & \times \frac{[\lambda_m / (\xi - b/2)] \sin(\lambda_m b / (\xi - b/2)) + h_{s_1} [1 - \cos(\lambda_m b / (\xi - b/2))]}{\lambda_m \sin(\lambda_m) + [h_{s_2} (\xi - (b/2)) - 1] \cos(\lambda_m)} \\ & \times \left[ \{ J_0(\xi_n r) - J_0(\xi_n a) \} + \frac{\xi_n}{2a} (r^2 - a^2) J_1(\xi_n a) \right] \\ & \times \frac{1 - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right]} + \frac{e^{-At} - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{A - K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right)}, \end{aligned} \tag{29}$$

$$\begin{aligned} \omega(r, t) &= \frac{-4K\alpha E}{D(1 - \nu)(\xi - (b/2))^2} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left\{ \frac{\lambda_m}{\xi_n^3 \{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \}} \right\} \\ & \times \frac{\left[ \frac{b}{2\lambda_m} (\xi - b/2)^2 \left\{ \frac{\lambda_m}{(\xi - (b/2))} \sin \left( \frac{\lambda_m b}{(\xi - (b/2))} \right) - h_{s_1} \left[ 1 + \cos \left( \frac{\lambda_m b}{(\xi - (b/2))} \right) \right] \right\} + \frac{(\xi - (b/2))^2}{\lambda_m^2} \left[ \lambda_m \left( \cos \left( \frac{\lambda_m b}{(\xi - (b/2))} \right) - 1 \right) + h_{s_1} (\xi - b/2) \sin \frac{\lambda_m b}{(\xi - (b/2))} \right]}{\lambda_m \sin(\lambda_m) + [h_{s_2} (\xi - (b/2)) - 1] \cos(\lambda_m)} \right] \end{aligned}$$

$$\begin{aligned} & \times \left[ \left( \frac{64}{a\xi_n^3} - \frac{8a}{\xi_n} \right) J_1(\xi_n a) - \frac{32}{\xi_n^2} J_0(\xi_n a) \right] \\ & \left[ J_0(\xi_n r) - \frac{r^2 \xi_n}{2(1+\nu)} \left\{ (1-\xi_n) J_0(\xi_n a) + \frac{(1-\nu)}{a} J_1(\xi_n a) \right\} - 1 \right] \\ & \times \frac{1 - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right]} + \frac{e^{-At} - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{A - K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right)}, \end{aligned} \tag{30}$$

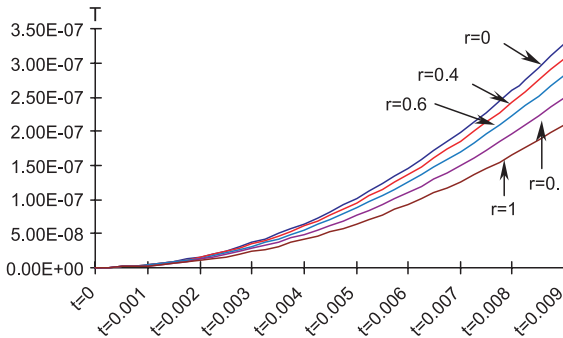
and

$$\begin{aligned} \theta &= \frac{-4k\alpha E}{Da(1-\nu^2)(\xi - (b/2))^2} \\ & \times \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \left[ \frac{\lambda_m \left[ \left( \frac{64}{a\xi_n^3} - \frac{8a}{\xi_n} \right) J_1(\xi_n a) - \frac{32}{\xi_n^2} J_0(\xi_n a) \right]}{\xi_n^2 \left\{ [J_0(\xi_n a)]^2 + [J_1(\xi_n a)]^2 \right\}} \right] \\ & \left[ \frac{b}{2\lambda_m} (\xi - b/2)^2 \left\{ \frac{\lambda_m}{(\xi - (b/2))} \sin \left( \frac{\lambda_m b}{\xi - (b/2)} \right) - h_{s1} \left[ 1 + \cos \left( \frac{\lambda_m b}{\xi - (b/2)} \right) \right] \right\} \right. \\ & \left. + \frac{(\xi - (b/2))^2}{\lambda_m^2} \left[ \lambda_m \left( \cos \left( \frac{\lambda_m b}{\xi - b/2} \right) - 1 \right) + h_{s1} (\xi - b/2) \sin \frac{\lambda_m b}{(\xi - b/2)} \right] \right] \\ & \times \frac{\lambda_m \sin(\lambda_m) + [h_{s2} (\xi - (b/2)) - 1] \cos(\lambda_m)}{\lambda_m \sin(\lambda_m) + [h_{s2} (\xi - (b/2)) - 1] \cos(\lambda_m)} \\ & \times [a(1+\nu) J_1(\xi_n r) + r \{ a(1-\xi_n) J_0(\xi_n a) + (1-\nu) J_1(\xi_n a) \}] \\ & \times \frac{1 - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{k \left[ \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right]} + \frac{e^{-At} - e^{-k \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right) t}}{A - K \left( \xi_n^2 + \frac{\lambda_m^2}{(\xi - (b/2))^2} \right)}, \end{aligned} \tag{31}$$

**6. Numerical results and discussions**

Numerical calculations have been carried out for a steel plate (SN 50C) for which the material constants are as follows:

$$\begin{aligned} a &= 1 \text{ m}, b = 0.2 \text{ m}, A = 0.3, \xi = 0.05 \text{ m}, \pi = 3.14, K = 15.9 \times 10^{-6} (\text{m}^2 \text{s}^{-1}), \\ h_{s1} &= 1, h_{s2} = 0, h_e = 1, \alpha = 11.6 \times 10^{-6} (\text{K}^{-1}), E = 215 \text{ (GPa)}, \nu = 0.281, \end{aligned}$$



**Figure 1.** Variation of temperature *T* versus time *t*.



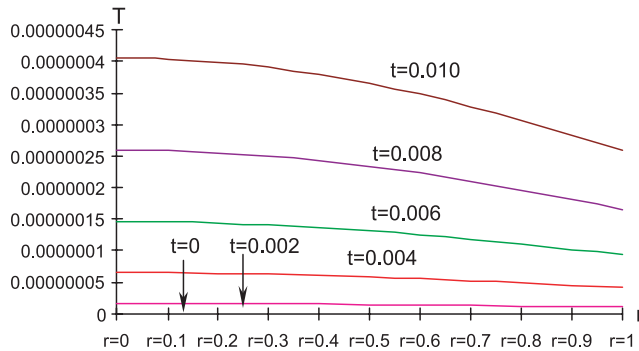


Figure 2. Variation of temperature  $T$  versus radius  $r$ .

and time  $t$  is in seconds. The plate is thin due to it being of one-fifth thickness of the largest dimension in the work of Nowinski (1978). The first five roots of the transcendental equation

$$-\xi J_1(\xi a) + h_e J_0(\xi a) = 0$$

(Özsisik 1968, p. 491) are  $\xi_1 = 1.2558$ ,  $\xi_2 = 4.0795$ ,  $\xi_3 = 7.1558$ ,  $\xi_4 = 10.2710$ ,  $\xi_5 = 13.3984$  and the first five roots of the transcendental equation

$$-\lambda \cos \lambda + h_{s_2}(\xi - b/2) \sin \lambda = 0$$

i.e.  $\lambda \cot \lambda = -c$ , where  $c = 0$  (constant) (Özsisik 1968, p. 482) are  $\lambda_1 = 1.5708$ ,  $\lambda_2 = 4.7124$ ,  $\lambda_3 = 7.8540$ ,  $\lambda_4 = 10.9956$ ,  $\lambda_5 = 14.1372$ . Using the numerical values of the above material constants and the roots of the transcendental equations, the temperature distribution, the thermal deflection and the angle of variation are evaluated. Due to the temperature effect on the upper surface, the fluctuations in deflection and angle of variation are shown. The variations are shown in figures 1 to 4.

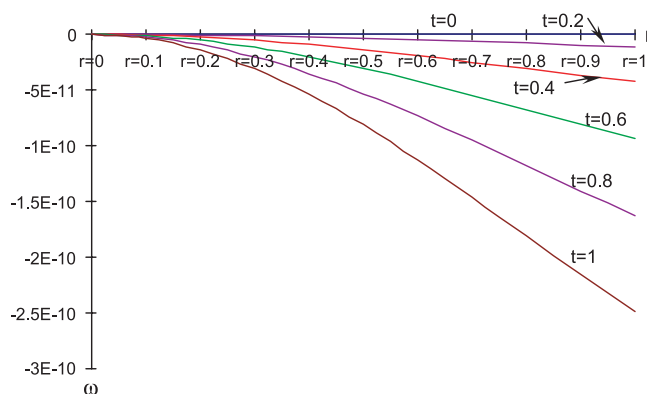
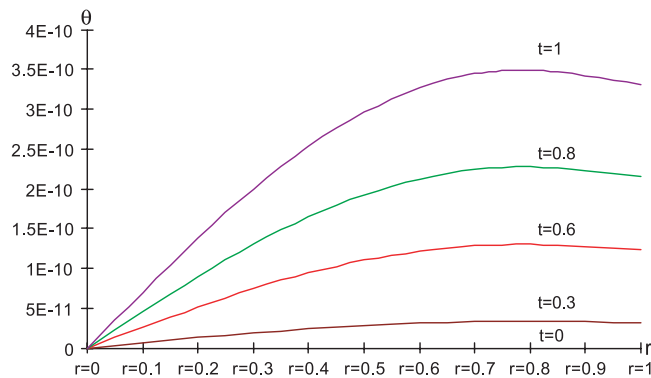


Figure 3. Variation of deflection  $\omega$  versus radius  $r$ .



**Figure 4.** Angle of variation  $\theta$  versus radius  $r$ .

## 7. Concluding remarks

In this work we have dealt with the determination of force component, thermal deflection and angle of variation of a thin circular plate on the upper surface due to heating. The expressions for the temperature distribution, unknown heating temperature, force component, thermal deflection and angle of variation are obtained in series form involving Bessel's functions. An integral transform technique is employed to solve this inverse problem. The numerical results are prescribed graphically for the temperature distribution, the thermal deflection and the angle of variation. This inverse problem may be useful in engineering applications particularly for industrial machines subjected to heating such as the main shaft of a lathe, turbines and rolling mills. Any particular case of special interest can be derived by assigning suitable values to the parameters and functions in the expressions (14), (15), (20), (22) and (23).

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