

## Geometry of the cotangent bundle with Sasakian metrics and its applications

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**Abstract.** The main aim of this paper is to study paraholomorphic Sasakian metric and Killing vector field with respect to the Sasakian metric in the cotangent bundle.

**Keywords.** Sasakian metric; cotangent bundle; vertical and horizontal lift; almost complex structure; Killing vector field.

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### 1. Introduction

Sasakian metrics on tangent bundle were introduced in 1958 by the Japanese geometer Sasaki [15]. Sasakian metrics (diagonal lifts of metrics) on tangent bundles were also studied in [4, 8, 16]. In a more general case of tensor bundles of type  $(1, q)$ ,  $(0, q)$  and  $(p, q)$ , Sasakian metrics and their geodesics are considered in [3, 10, 11]. Curvature properties for the Sasakian metric of the tangent bundle are given in [1, 4, 6, 9, 16]. The geometry of Sasaki metric is studied for the cotangent bundle in [13, 14, 16]. This paper is concerned with paraholomorphic Sasakian metric and Killing vector field property of Sasakian metrics in the cotangent bundle.

### 2. Preliminaries

Let  $M^n$  be an  $n$ -dimensional Riemannian manifold of class  $C^\infty$  and with metric  $g$ ,  $T^*M^n$  its cotangent bundle and  $\pi$  the natural projection  $T^*M^n \rightarrow M^n$ . A system of local coordinates  $(U, x^i)$ ,  $i = 1, \dots, n$  in  $M^n$  induces on  $T^*M^n$  a system of local coordinates  $(\pi^{-1}(U), x^i, x^{\bar{i}} = p_i)$ ,  $\bar{i} := n + i = n + 1, \dots, 2n$ , where  $x^{\bar{i}} = p_i$  is the component of covectors  $p$  in each cotangent space  $T_x^*M^n$ ,  $x \in U$  with respect to the natural coframe  $\{dx^i\}$ .

We denote by  $\mathfrak{S}_s^r(M^n)(\mathfrak{S}_s^r(T^*M^n))$  the module over  $F(M^n)(F(T^*M^n))$  of  $C^\infty$  tensor fields of type  $(r, s)$ , where  $F(M^n)(F(T^*M^n))$  is the ring of real-valued  $C^\infty$  functions on  $M^n(T^*M^n)$ .

Let  $X = X^i \frac{\partial}{\partial x^i}$  and  $\omega = \omega_i dx^i$  be the local expressions in  $U \subset M^n$  of a vector and a covector (1-form) fields  $X \in \mathfrak{S}_0^1(M^n)$  and  $\omega \in \mathfrak{S}_1^0(M^n)$ , respectively. Then the complete and horizontal lifts  ${}^C X, {}^H X \in \mathfrak{S}_0^1(T^*M^n)$  of  $X \in \mathfrak{S}_0^1(M^n)$  and the vertical lift  ${}^V \omega \in \mathfrak{S}_0^1(T^*M^n)$  of  $\omega \in \mathfrak{S}_1^0(M^n)$  are given, respectively by

$${}^C X = X^i \frac{\partial}{\partial x^i} - \sum_i p_h \partial_i X^h \frac{\partial}{\partial x^{\bar{i}}}, \quad (1)$$

$${}^H X = X^i \frac{\partial}{\partial x^i} + \sum_i p_h \Gamma_{ij}^h X^j \frac{\partial}{\partial x^{\bar{i}}}, \quad (2)$$

$${}^V \omega = \sum_i \omega_i \frac{\partial}{\partial x^{\bar{i}}}, \quad (3)$$

with respect to the natural frame  $\left\{ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^{\bar{i}}} \right\}$ , where  $\Gamma_{ij}^h$  are the components of the Levi-Civita connection  $\nabla_g$  on  $M^n$  (see [16] for more details).

For each  $x \in M^n$ , the scalar product  $g^{-1} = (g^{ij})$  is defined on the cotangent space  $\pi^{-1}(x) = T_x^*M^n$  by

$$g^{-1}(\omega, \theta) = g^{ij} \omega_i \theta_j$$

for all  $\omega, \theta \in \mathfrak{S}_1^0(M^n)$ .

A Sasakian metric  ${}^S g$  is defined on  $T^*M^n$  by the following three equations:

$${}^S g({}^V \omega, {}^V \theta) = {}^V(g^{-1}(\omega, \theta)) = g^{-1}(\omega, \theta) \circ \pi, \quad (4)$$

$${}^S g({}^V \omega, {}^H Y) = 0, \quad (5)$$

$${}^S g({}^H X, {}^H Y) = {}^V(g(X, Y)) = g(X, Y) \circ \pi, \quad (6)$$

for any  $X, Y \in \mathfrak{S}_0^1(M^n)$  and  $\omega, \theta \in \mathfrak{S}_1^0(M^n)$ . Since any tensor field of type (0,2) on  $T^*M^n$  is completely determined by its action on vector fields of type  ${}^H X$  and  ${}^V \omega$  (see p. 280 of [16]), it follows that  ${}^S g$  is completely determined by its eqs (4), (5) and (6).

### 3. Levi-Civita connection of ${}^S g$

In  $U \subset M^n$ , we put

$$X_{(i)} = \frac{\partial}{\partial x^i}, \quad \theta^{(i)} = dx^i, \quad i = 1, \dots, n.$$

Then from (2) and (3) we see that  ${}^H X_{(i)}$  and  ${}^V \theta^{(i)}$  have respectively local expressions of the form

$$\tilde{e}_{(i)} = {}^H X_{(i)} = \frac{\partial}{\partial x^i} + \sum_h p_a \Gamma_{hi}^a \frac{\partial}{\partial x^{\bar{h}}}, \quad (7)$$

$$\tilde{e}_{(\bar{i})} = {}^V \theta^{(i)} = \frac{\partial}{\partial x^{\bar{i}}}. \quad (8)$$

We call the set  $\{\tilde{e}_{(\alpha)}\} = \{\tilde{e}_{(i)}, \tilde{e}_{(\bar{i})}\} = \{{}^H X_{(i)}, {}^V \theta^{(i)}\}$  the frame adapted to Levi-Civita connection  $\nabla_g$ . The indices  $\alpha, \beta, \dots = 1, \dots, 2n$  indicate the indices with respect to the adapted frame.

Now from the equations (1), (2), (3), (7) and (8), we see that  ${}^H X$  and  ${}^V \omega$  have components

$${}^C X = X^i \tilde{e}_{(i)} - \sum_i p_h \nabla_i X^h \tilde{e}_{(\bar{i})}, \quad {}^C X = ({}^C X^\alpha) = \begin{pmatrix} X^i \\ -p_h \nabla_i X^h \end{pmatrix}, \quad (9)$$

$${}^H X = X^i \tilde{e}_{(i)}, \quad {}^H X = ({}^H X^\alpha) = \begin{pmatrix} X^i \\ 0 \end{pmatrix}, \quad (10)$$

$${}^V \omega = \sum_i \omega_i \tilde{e}_{(\bar{i})}, \quad {}^V \omega = ({}^V \omega^\alpha) = \begin{pmatrix} 0 \\ \omega_i \end{pmatrix}, \quad (11)$$

with respect to the adapted frame  $\{\tilde{e}_{(\alpha)}\}$ , where  $X^i$  and  $\omega_i$  are the local components of  $X \in \mathfrak{S}_0^1(M^n)$  and  $\omega \in \mathfrak{S}_1^0(M^n)$ , respectively.

From (4), (5) and (6) we see that

$$\begin{aligned} {}^S g_{\bar{i}\bar{j}} &= {}^S g(\tilde{e}_{(\bar{i})}, \tilde{e}_{(\bar{j})}) = {}^V (g^{-1}(dx^i, dx^j)) = g^{ij}, \\ {}^S g_{\bar{i}j} &= {}^S g(\tilde{e}_{(\bar{i})}, \tilde{e}_{(j)}) = 0, \\ {}^S g_{ij} &= {}^S g(\tilde{e}_{(i)}, \tilde{e}_{(j)}) = {}^V (g(\partial_i, \partial_j)) = g_{ij}, \end{aligned}$$

i.e.  ${}^S g$  has components

$${}^S g = \begin{pmatrix} g_{ij} & 0 \\ 0 & g^{\bar{i}\bar{j}} \end{pmatrix} \quad (12)$$

with respect to the adapted frame  $\{\tilde{e}_{(\alpha)}\}$ .

We now consider local 1-forms  $\tilde{\omega}^\alpha$  in  $\pi^{-1}(U)$  defined by

$$\tilde{\omega}^\alpha = \bar{A}^\alpha_B dx^B,$$

where

$$A^{-1} = (\bar{A}^\alpha_B) = \begin{pmatrix} \bar{A}^i_j & \bar{A}^i_{\bar{j}} \\ \bar{A}^{\bar{i}}_j & \bar{A}^{\bar{i}}_{\bar{j}} \end{pmatrix} = \begin{pmatrix} \delta_j^i & 0 \\ -p_a \Gamma_{ij}^a & \delta_i^{\bar{j}} \end{pmatrix}. \quad (13)$$

The matrix (13) is the inverse of the matrix

$$A = (A_\beta^A) = \begin{pmatrix} A_j^i & A_{\bar{j}}^i \\ A_j^{\bar{i}} & A_{\bar{j}}^{\bar{i}} \end{pmatrix} = \begin{pmatrix} \delta_j^i & 0 \\ p_a \Gamma_{ij}^a & \delta_i^{\bar{j}} \end{pmatrix} \quad (14)$$

of the transformation  $\tilde{e}_\beta = A_\beta^A \partial_A$  (see (7) and (8)). We easily see that the set  $\{\tilde{\omega}^\alpha\}$  is the coframe dual to the adapted frame  $\{\tilde{e}_{(\beta)}\}$ , i.e.,  $\tilde{\omega}^\alpha(\tilde{e}_{(\beta)}) = \bar{A}^\alpha_B A_\beta^B = \delta_\beta^\alpha$ .

Since the adapted frame  $\{\tilde{e}_{(\beta)}\}$  is non-holonomic, we put

$$[\tilde{e}_\gamma, \tilde{e}_\beta] = \Omega_{\gamma\beta}^\alpha \tilde{e}_\alpha$$

from which we have

$$\Omega_{\gamma\beta}{}^\alpha = (\tilde{e}_\gamma A_\beta{}^A - \tilde{e}_\beta A_\gamma{}^A)\bar{A}^{\alpha}{}_A.$$

According to (7), (8), (13) and (14), the components of non-holonomic object  $\Omega_{\gamma\beta}{}^\alpha$  are given by

$$\begin{cases} \Omega_{lj}{}^{\bar{i}} = -\Omega_{\bar{j}l}{}^{\bar{i}} = -\Gamma_{li}^{\bar{j}}, \\ \Omega_{lj}{}^{\bar{i}} = p_a R_{lji}{}^a, \end{cases} \quad (15)$$

all the others being zero, where  $R_{lji}{}^a$  is the local component of the curvature tensor  $R$  of  $\nabla_g$ .

Let  ${}^S\nabla$  be the Levi-Civita connection determined by the Sasakian metric  ${}^Sg$ . We put

$${}^S\nabla_{\tilde{e}_\gamma}\tilde{e}_\beta = {}^S\Gamma_{\gamma\beta}{}^\alpha\tilde{e}_\alpha.$$

From the equation  ${}^S\nabla_X Y - {}^S\nabla_Y X = [X, Y]$ ,  $\forall X, Y \in \mathfrak{S}_0^1(T^*M^n)$  we have

$${}^S\Gamma_{\gamma\beta}{}^\alpha - {}^S\Gamma_{\beta\gamma}{}^\alpha = \Omega_{\gamma\beta}{}^\alpha. \quad (16)$$

The equation  $({}^S\nabla_X {}^Sg)(Y, Z) = 0$  has the form

$$\tilde{e}_\delta {}^Sg_{\gamma\beta} - {}^S\Gamma_{\delta\gamma}{}^\varepsilon {}^Sg_{\varepsilon\beta} - {}^S\Gamma_{\delta\beta}{}^\varepsilon {}^Sg_{\gamma\varepsilon} = 0. \quad (17)$$

with respect to the adapted frame  $\{\tilde{e}_{(\alpha)}\}$ . We have from (15) and (17)

$${}^S\Gamma_{\gamma\beta}{}^\alpha = \frac{1}{2} {}^Sg^{\alpha\varepsilon} (\tilde{e}_\gamma {}^Sg_{\varepsilon\beta} + \tilde{e}_\beta {}^Sg_{\gamma\varepsilon} - \tilde{e}_\varepsilon {}^Sg_{\gamma\beta}) + \frac{1}{2} (\Omega_{\gamma\beta}{}^\alpha + \Omega^\alpha{}_{\gamma\beta} + \Omega^\alpha{}_{\beta\gamma}), \quad (18)$$

where  $\Omega^\alpha{}_{\gamma\beta} = {}^Sg^{\alpha\varepsilon} {}^Sg_{\delta\beta} \Omega_{\varepsilon\gamma}{}^\delta$  and  $({}^Sg)^{-1} = ({}^Sg^{\alpha\beta}) = \begin{pmatrix} g^{ij} & 0 \\ 0 & g_{ij} \end{pmatrix}$ .

Taking account of (7), (8), (12), (15), we obtain from (18),

$$\begin{cases} {}^S\Gamma_{ji}^h = \Gamma_{ji}^h, & {}^S\Gamma_{\bar{j}\bar{i}}^h = {}^S\Gamma_{\bar{j}\bar{i}}^{\bar{h}} = {}^S\Gamma_{\bar{j}\bar{i}}^{\bar{h}} = 0, \\ {}^S\Gamma_{\bar{j}\bar{i}}^h = \frac{1}{2} p_m R^h{}_{j.}{}^{im}, & {}^S\Gamma_{\bar{j}\bar{i}}^{\bar{h}} = \frac{1}{2} p_m R^{\bar{h}}{}_{i.}{}^{jm}, \\ {}^S\Gamma_{ji}^{\bar{h}} = \frac{1}{2} p_m R_{jih}{}^m, & {}^S\Gamma_{\bar{j}\bar{i}}^{\bar{h}} = -\Gamma_{jh}^i. \end{cases} \quad (19)$$

Let  $\tilde{X}, \tilde{Y} \in \mathfrak{S}_0^1(T^*M^n)$  and  $\tilde{X} = \tilde{X}^\alpha \tilde{e}_\alpha$ ,  $\tilde{Y} = \tilde{Y}^\beta \tilde{e}_\beta$ . Then the covariant derivative  ${}^S\nabla_{\tilde{Y}} \tilde{X}$  along  $\tilde{Y}$  has components

$${}^S\nabla_{\tilde{Y}} \tilde{X}^\alpha = \tilde{Y}^\gamma \tilde{e}_\gamma \tilde{X}^\alpha + {}^S\Gamma_{\gamma\beta}{}^\alpha \tilde{X}^\beta \tilde{Y}^\gamma, \quad (20)$$

with respect to adapted frame  $\{\tilde{e}_{(\alpha)}\}$ .

Using (7), (8), (10), (11), (19) and (20) we have as follows.

**Theorem 1 [14].** *Let  $M^n$  be a Riemannian manifold with metric  $g$  and  ${}^S\nabla$  be the Levi-Civita connection of the cotangent bundle  $T^*M^n$  equipped with the Sasakian metric  ${}^Sg$ . Then  ${}^S\nabla$  satisfies*

(i)  ${}^S\nabla_{\omega} \vee \theta = 0$ ,

- (ii)  $S\nabla_{v_\omega}^H Y = \frac{1}{2}H(R(\tilde{p}, \tilde{\omega})Y)$ ,
- (iii)  $S\nabla_{H_X}^V \theta = V(\nabla_X \theta) + \frac{1}{2}H(R(\tilde{p}, \tilde{\theta})X)$
- (iv)  $S\nabla_{H_X}^H Y = H(\nabla_X Y) + \frac{1}{2}V(pR(X, Y))$

for all  $X, Y \in \mathfrak{S}_0^1(M^n)$ ,  $\omega, \theta \in \mathfrak{S}_1^0(M^n)$ , where  $\tilde{\omega} = g^{-1} \circ \omega \in \mathfrak{S}_0^1(M^n)$ ,  $\tilde{\theta} = g^{-1} \circ \theta \in \mathfrak{S}_0^1(M^n)$ ,  $\tilde{p} = g^{-1} \circ p \in \mathfrak{S}_0^1(M^n)$ .

#### 4. Killing vector fields

A vector field  $X \in \mathfrak{S}_0^1(M^n)$  is called Killing vector field (or infinitesimal isometry) if  $L_X g = 0$ , and  $X$  is called the infinitesimal affine transformation if  $L_X \nabla_g = 0$ . A Killing vector field is necessarily an infinitesimal affine transformation, i.e. we have  $L_X \nabla_g = 0$  as a consequence of  $L_X g = 0$  [16].

**Theorem 2** [2]. *Necessary and sufficient conditions in order that the*

- (a) *complete*  ${}^C X \in \mathfrak{S}_0^1(T^*M^n)$ ,
- (b) *horizontal*  ${}^H X \in \mathfrak{S}_0^1(T^*M^n)$  and
- (c) *vertical*  ${}^V \omega \in \mathfrak{S}_1^0(T^*M^n)$

*lifts to  $T^*M^n$  with the metric  ${}^S g$ , of a vector field  $X$  and covector field  $\omega$  in  $M^n$  be a Killing vector field in  $T^*M^n$  such that*

- (a)  $X$  is a Killing vector field in  $M^n$ ,
- (b)  $X$  is a Killing vector field with vanishing second covariant derivative in  $M^n$  and
- (c)  $\omega$  is parallel  $M^n$ .

Let  $X$  and  $Y$  be vector fields in  $M^n$ . If  $X$  and  $Y$  are Killing vector fields in  $M^n$ , from the definition of the Killing vector field, we have

$$L_{[X, Y]}g = L_X(L_Y g) - L_Y(L_X g) = 0,$$

i.e.  $[X, Y]$  is an infinitesimal isometry in  $M^n$  [5].

It is well known that (p. 238, p. 277 of [16])

$$\begin{aligned} [{}^C X, {}^H X] &= {}^H[X, Y] + {}^V(p(L_X \nabla)Y), \\ [{}^C X, {}^V \omega] &= {}^V(L_X \omega), \\ [{}^C X, {}^C Y] &= {}^C[X, Y], \end{aligned} \tag{21}$$

where  $(L_X \nabla)Y = \nabla_Y \nabla X + R(X, Y)$  and  $(L_X \nabla)(Y, Z) = L_X(\nabla_Y Z) - \nabla_{[X, Y]}Z$ .

Using (21), we compute the Lie derivatives of the metric  ${}^S g$  with respect to  ${}^V(L_X \omega)$  and  ${}^C[X, Y]$ :

$$\begin{aligned} L_{[{}^C X, Y]} {}^S g &= L_{[{}^C X, {}^C Y]} {}^S g = L_{{}^C X}(L_{{}^C Y} {}^S g) - L_{{}^C Y}(L_{{}^C X} {}^S g), \\ L_{{}^V(L_X \omega)} {}^S g &= L_{[{}^C X, {}^V \omega]} {}^S g = L_{{}^C X}(L_{{}^V \omega} {}^S g) - L_{{}^V \omega}(L_{{}^C X} {}^S g). \end{aligned} \tag{22}$$

Using Theorem 2 and (22), we get as follows.

**Theorem 3.** *Sufficient conditions in order that the vertical lift of a covector field  $L_X\omega$  and complete lift of a vector field  $[X, Y]$  in  $M^n$  to  $T^*M^n$  be a Killing vector with metric  ${}^Sg$  are that  $X$  and  $Y$  are Killing vector fields with vanishing second covariant derivative and  $\omega$  is parallel in  $M^n$ .*

Let  $X$  be infinitesimal affine transformation in  $M^n$   $(L_X\nabla) = 0$ . Then  $[{}^C X, {}^H X] = {}^H[X, Y]$  and

$$L_{{}^H[X, Y]} {}^Sg = L_{{}^C X, {}^H Y} {}^Sg = L_{{}^C X}(L_{{}^H Y} {}^Sg) - L_{{}^H Y}(L_{{}^C X} {}^Sg).$$

Using Theorem 2 and the last equation, we have as follows.

**Theorem 4.** *Sufficient conditions in order that the horizontal lift of a vector field  $[X, Y]$  in  $M^n$  to  $T^*M^n$  be a Killing vector with metric  ${}^Sg$  are that  $X$  and  $Y$  are a Killing vector fields with vanishing second covariant derivative in  $M^n$ .*

### 5. On almost paracomplex structures of special type in the cotangent bundle

An almost paracomplex manifold is an almost product manifold  $(M^n, \varphi)$ ,  $\varphi^2 = I$ , such that the two eigenbundles  $T^+M^n$  and  $T^-M^n$  associated to the two eigenvalues  $+1$  and  $-1$  of  $\varphi$ , respectively, have the same rank. Note that the dimension of an almost paracomplex manifold is necessarily even. Considering the paracomplex structure  $\varphi$ , we obtain the set  $\{I, \varphi\}$  on  $M^n$ , which is an isomorphic representation algebra of order 2, which is called the algebra of paracomplex (or double) numbers and is denoted by  $R(j)$ ,  $j^2 = 1$ .

A tensor field  $\omega \in \mathfrak{S}_q^0(M^{2n})$  is said to be a pure with respect to the paracomplex structure  $\varphi$ , if

$$\omega(\varphi X_1, X_2, \dots, X_q) = \omega(X_1, \varphi X_2, \dots, X_q) = \omega(X_1, X_2, \dots, \varphi X_q)$$

for any  $X_1, X_2, \dots, X_q \in \mathfrak{S}_0^1(M^{2n})$ .

We define the operator  $\phi_\varphi$  associated with  $\varphi$  and apply to the pure tensor field  $\omega$  :

$$\begin{aligned} (\phi_\varphi\omega)(Y, X_1, X_2, \dots, X_q) &= (\varphi Y)(\omega(X_1, X_2, \dots, X_q)) \\ &\quad - Y(\omega(\varphi X_1, X_2, \dots, X_q)) \\ &\quad + \omega((L_{X_1}\varphi)Y, X_2, \dots, X_q) \\ &\quad + \dots + \omega(X_1, X_2, \dots, (L_{X_q}\varphi)Y). \end{aligned} \tag{23}$$

where  $L_X$  denotes the Lie derivative with respect to  $X$ . We note that  $\phi_\varphi\omega \in \mathfrak{S}_{q+1}^0(M^{2n})$ . If  $\phi_\varphi\omega = 0$ , then  $\omega$  is said to be almost paraholomorphic with respect to the paracomplex algebra  $R(j)$  (see [7, 9, 12, 14]).

#### DEFINITION 1

In a manifold with almost paracomplex structure  $\varphi$ , a vector field  $X$  is called an almost paraholomorphic vector field if  $L_X\varphi = 0$ .

Let  $F \in \mathfrak{S}_1^1(M^n)$ . We define a tensor field  ${}^D F$  of type (1,1) in  $T^*M^n$  by

$${}^D F^H X = {}^H(FX), \quad {}^D F^V \omega = -{}^V(\omega \circ F) = -{}^V(\omega F) \tag{24}$$

for any  $X \in \mathfrak{S}_0^1(M^n)$  and  ${}^V\omega \in \mathfrak{S}_1^0(M^n)$ . We call  ${}^D F$  the diagonal lift of the tensor field  $F$ .  ${}^D F$  has components

$${}^D F = \begin{pmatrix} F_i^h & 0 \\ 0 & -F_h^i \end{pmatrix} \quad (25)$$

with respect to the adapted frame  $\tilde{e}_{(\alpha)}$ . The diagonal lift  ${}^D I$  of identity tensor field  $I$  of type (1,1) has the components

$${}^D I = \begin{pmatrix} \delta_j^i & 0 \\ 2p_a \Gamma_{ij}^a & -\delta_j^i \end{pmatrix} \quad (26)$$

with respect to the induced coordinates and satisfies  ${}^D I^2 = I$ . Thus  ${}^D I$  is an almost product structure determining the horizontal distribution and the distribution consisting of the tangent planes to fibres [16].

We put

$$S(\tilde{X}, \tilde{Y}) = S_g({}^D I \tilde{X}, \tilde{Y}) - S_g(\tilde{X}, {}^D I \tilde{Y})$$

If  $S(\tilde{X}, \tilde{Y}) = 0$ , for all vector fields  $\tilde{X}$  and  $\tilde{Y}$  which are of the form  ${}^V\omega, {}^V\theta$  or  ${}^H X, {}^H Y$ , then  $S = 0$ . By virtue of  ${}^D I {}^V\omega = -{}^V\omega, {}^D I {}^H X = {}^H X$  and (4), (5) and (6), we have

$$\begin{aligned} S({}^V\omega, {}^V\theta) &= S_g(-{}^V\omega, {}^V\theta) - S_g({}^V\omega, -{}^V\theta) = 0, \\ S({}^V\omega, {}^H X) &= S_g(-{}^V\omega, {}^H X) - S_g({}^V\omega, {}^H X) = 0, \\ S({}^H X, {}^V\theta) &= S_g({}^H X, {}^V\theta) - S_g({}^H X, -{}^V\theta) = 0, \\ S({}^H X, {}^H Y) &= S_g({}^H X, {}^H Y) - S_g({}^H X, {}^H Y) = 0, \end{aligned}$$

i.e.  $S_g$  is pure metric with respect to  ${}^D I$ .

**Theorem 5.**  $(T^*M^n, {}^D I, S_g)$  is an almost paracomplex Riemannian manifold.

It is well known that (p. 238, p. 277 of [16])

$$\begin{aligned} {}^V\omega {}^V f &= 0, & {}^H X {}^V f &= {}^V(Xf), \\ [{}^H X, {}^V\omega] &= {}^V(\nabla_X \omega), & [{}^V\omega, {}^V\theta] &= 0, \\ [{}^H X, {}^H Y] &= {}^H[X, Y] + \gamma R(X, Y) = {}^H[X, Y] + {}^V(pR(X, Y)), \end{aligned} \quad (27)$$

$pR(X, Y) = (p_i(R(X, Y)^i_j))$  and

$$\begin{aligned} {}^D I {}^V(pR(X, Y)) &= -{}^V(pR(X, Y)), \\ S_g({}^V(pR(X, Y)), {}^H Z) &= 0. \end{aligned} \quad (28)$$

From (23) we have

- (i)  $(\phi_{D_I} S_g)({}^V\omega, {}^V\theta, {}^V\xi) = ({}^D I {}^V\omega)(S_g({}^V\theta, {}^V\xi)) - {}^V\omega(S_g({}^D I {}^V\theta, {}^V\xi))$   
 $+ S_g((L_{V\theta} {}^D I) {}^V\omega, {}^V\xi) + S_g({}^V\theta, ((L_{V\xi} {}^D I) {}^V\omega)) = 0,$
- (ii)  $(\phi_{D_I} S_g)({}^V\omega, {}^V\theta, {}^H X) = ({}^D I {}^V\omega)(S_g({}^V\theta, {}^H X)) - {}^V\omega(S_g({}^D I {}^V\theta, {}^H X))$   
 $+ S_g((L_{V\theta} {}^D I) {}^V\omega, {}^H X) + S_g({}^V\theta, ((L_{H X} {}^D I) {}^V\omega)) = 0,$

- (iii)  $(\phi_{D_I} S g)^{(\nabla \omega, {}^H X, \nabla \xi)} = ({}^D I \nabla \omega) (S g({}^H X, \nabla \xi)) - \nabla \omega (S g({}^D I {}^H X, \nabla \xi))$   
 $+ S g((L_{{}^H X} {}^D I) \nabla \omega, \nabla \xi) + S g({}^H X, ((L_{\nabla \xi} {}^D I) \nabla \omega)) = 0,$
- (iv)  $(\phi_{D_I} S g)^{({}^H X, \nabla \omega, \nabla \theta)} = ({}^D I {}^H X) (S g(\nabla \omega, \nabla \theta)) - {}^H X (S g({}^D I \nabla \omega, \nabla \theta))$   
 $+ S g((L_{\nabla \omega} {}^D I) {}^H X, \nabla \theta) + S g(\nabla \omega, ((L_{\nabla \theta} {}^D I) {}^H X)) = 0,$
- (v)  $(\phi_{D_I} S g)^{({}^H X, {}^H Y, {}^H Z)} = ({}^D I {}^H X) (S g({}^H Y, {}^H Z)) - {}^H X (S g({}^D I {}^H Y, {}^H Z))$   
 $+ S g((L_{{}^H Y} {}^D I) {}^H X, {}^H Z) + S g({}^H Y, ((L_{{}^H Z} {}^D I) {}^H X)) = 0,$
- (vi)  $(\phi_{D_I} S g)^{(\nabla \omega, {}^H X, {}^H Y)} = ({}^D I \nabla \omega) (S g({}^H X, {}^H Y)) - \nabla \omega (S g({}^D I {}^H X, {}^H Y))$   
 $+ S g((L_{{}^H X} {}^D I) \nabla \omega, {}^H Y) + S g({}^H X, ((L_{{}^H Y} {}^D I) \nabla \omega)) = 0,$
- (vii)  $(\phi_{D_I} S g)^{({}^H X, {}^H Y, \nabla \omega)} = ({}^D I {}^H X) (S g({}^H Y, \nabla \omega)) - {}^H X (S g({}^D I {}^H Y, \nabla \omega))$   
 $+ S g((L_{{}^H Y} {}^D I) {}^H X, \nabla \omega) + S g({}^H Y, ((L_{\nabla \omega} {}^D I) {}^H X))$   
 $= 2 S g(\nabla \omega, \nabla (pR(X, Y))) = 2g^{-1}(\omega, (pR(X, Y))),$
- (viii)  $(\phi_{D_I} S g)^{({}^H X, \nabla \omega, {}^H Y)} = 2 S g(\nabla \omega, \nabla (pR(X, Y))) = 2g^{-1}(\omega, (pR(X, Y))),$

is analogous to (vii).

Therefore we have as follows.

**Theorem 6.** *The almost paracomplex Riemannian manifold  $(T^*M^n, {}^D I, S g)$  is paraholomorphic if and only if  $M^n$  is flat.*

We now consider the Lie derivative of  ${}^D I$  with respect to the complete lift  ${}^C X$ , we obtain

$$\begin{aligned} (L_{{}^C X} {}^D I) \nabla \theta &= L_{{}^C X} ({}^D I \nabla \theta) - {}^D I (L_{{}^C X} \nabla \theta) = -L_{{}^C X} \nabla \theta - {}^D I (L_{{}^C X} \nabla \theta) \\ &= -\nabla (L_X \theta) - {}^D I \nabla (L_X \theta) = 0, \\ (L_{{}^C X} {}^D I) {}^H Y &= L_{{}^C X} ({}^D I {}^H Y) - {}^D I (L_{{}^C X} {}^H Y) = L_{{}^C X} {}^H Y - {}^D I (L_{{}^C X} {}^H Y) \\ &= {}^H [X, Y] + \nabla (p(L_X \nabla) Y) - {}^H [X, Y] + \nabla (p(L_X \nabla) Y), \\ &= 2 \nabla (p(L_X \nabla) Y). \end{aligned}$$

Thus using Definition 1, we have as follows.

**Theorem 7.** *If  $X$  is an infinitesimal affine transformation of a Riemannian manifold  $M^n$ , i.e., if  $L_X \nabla = 0$ , then its complete lift  ${}^C X$  to the cotangent bundle  $T^*M^n$  is an almost paraholomorphic vector field with respect to the almost paracomplex structure  $({}^D I, S g)$ .*

For almost paracomplex structure the integrability is equivalent to the vanishing of the Nijenhuis tensor [12],

$$N_\varphi(X, Y) = [\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + [X, Y].$$

Then using (27), we have

$$\begin{aligned} N_{D_I}({}^H X, {}^H Y) &= [{}^D I {}^H X, {}^D I {}^H Y] - {}^D I [{}^D I {}^H X, {}^H Y] - {}^D I [{}^H X, {}^D I {}^H Y] \\ &\quad + {}^D I^2 [{}^H X, {}^H Y] \\ &= [{}^H X, {}^H Y] - {}^D I [{}^H X, {}^H Y] - {}^D I [{}^H X, {}^H Y] + [{}^H X, {}^H Y] \end{aligned}$$



$$\begin{aligned}
&= 2({}^H[X, Y] + {}^V(pR(X, Y))) - 2({}^H[X, Y] - {}^V(pR(X, Y))) \\
&= 4{}^V(pR(X, Y)), \\
N_{D_I}({}^H X, {}^V \omega) &= [{}^D I {}^H X, {}^D I {}^V \omega] - {}^D I[{}^D I {}^H X, {}^V \omega] - {}^D I[{}^H X, {}^D I {}^V \omega] \\
&\quad + {}^D I^2[{}^H X, {}^V \omega] \\
&= 0, \\
N_{D_I}({}^V \omega, {}^H X) &= [{}^D I {}^V \omega, {}^D I {}^H X] - {}^D I[{}^D I {}^V \omega, {}^H X] - {}^D I[{}^V \omega, {}^D I {}^H X] \\
&\quad + {}^D I^2[{}^V \omega, {}^H X] \\
&= 0, \\
N_{D_I}({}^V \omega, {}^V \theta) &= [{}^D I {}^V \omega, {}^D I {}^V \theta] - {}^D I[{}^D I {}^V \omega, {}^V \theta] - {}^D I[{}^V \omega, {}^D I {}^V \theta] \\
&\quad + {}^D I^2[{}^V \omega, {}^V \theta] \\
&= 0.
\end{aligned}$$

$N_{D_I}(\tilde{X}, \tilde{Y}) = 0$  if and only if  $M^n$  is locally flat. Thus we have as follows.

**Theorem 8.** *Let  $(M^n, g)$  be a Riemannian manifold and  $T^*M^n$  be its cotangent bundle equipped with the Sasakian metric  ${}^S g$ . Then the almost paracomplex structure  ${}^D I$  is integrable if and only if  $M^n$  is locally flat.*

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